

**SERIES  
680XXB  
SYNTHESIZED CW GENERATOR  
GPIB PROGRAMMING MANUAL**

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# MANUAL CHANGES



## **MANUAL:**

**Title:** Series 680XXB Synthesized CW Generator GPIB Programming Manual

**Part Number:** 10370-10266

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## **CHANGE PACKET**

**Part Number:** 10900-00311

## **INSTRUCTIONS**

1. Make the manual changes listed below. The changes are listed in numerical order by page number. Effectivity is all 680XXB models with Firmware Version 3.43 and above and 680X5B models with Firmware Version 1.30 and above.
2. The replacement pages provided are for technical changes to the manual. The black bar or bars in the replacement page margins shows the area in which the changes were made.

## **CHANGE 1, February 2000**

1. **Page 2-5**  
Replace with enclosed pages 2-5 and 2-6, Changed: February 2000.
2. **Pages 2-34 and 2-35**  
Replace with enclosed pages 2-33 thru 2-36, Changed: February 2000.
3. **Page A-7**  
Replace with enclosed pages A-7 thru A-10, Changed: February 2000.

PCO: MI001654

# DECLARATION OF CONFORMITY

**Manufacturer's Name:** ANRITSU COMPANY

**Manufacturer's Address:** Microwave Measurements Division  
490 Jarvis Drive  
Morgan Hill, CA 95037-2809  
USA

declares that the product specified below:

**Product Name:** Synthesized CW / Sweep / Signal Generator

**Model Number:** 680XXB, 681XXB, 682XXB, 683XXB

conforms to the requirement of:

EMC Directive 89/336/EEC as amended by Council Directive 92/31/EEC & 93/68/EEC  
Low Voltage Directive 73/23/EEC as amended by Council directive 93/68/EEC

## **Electromagnetic Interference:**

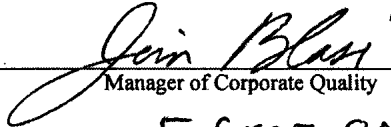
Emissions: CISPR 11:1990/EN55011:1991 Group 1 Class A

Immunity: IEC 1000-4-2:1995/prEN50082-1:1995 - 4kV CD, 8kV AD  
IEC 1000-4-3:1993/ENV50140:1994 - 3V/m  
IEC 1000-4-4:1995/prEN50082-1:1995 - 0.5kV SL, 1kV PL  
IEC 1000-4-5:1995/prEN50082-1:1995 - 0.5kV - 1kV LN  
0.5kV - 1kV NG  
0.5kV - 1kV GL

## **Electrical Safety Requirement:**

Product Safety: IEC 1010-1:1990 + A1/EN61010-1:1993

Morgan Hill, CA

  
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European Contact: For Anritsu product EMC & LVD information, contact Anritsu LTD, Rutherford Close, Stevenage Herts, SG1 2EF UK, (FAX 44-1438-740202)

# ***Table of Contents***

---

## ***Chapter 1 - General GPIB Information***

|     |  |      |
|-----|--|------|
| 1-1 | SCOPE OF MANUAL . . . . .                              | 1-3  |
|     | Electronic Manual . . . . .                            | 1-3  |
| 1-2 | INTRODUCTION . . . . .                                 | 1-3  |
| 1-3 | IEEE-488 INTERFACE BUS DESCRIPTION . . . . .           | 1-5  |
|     | Functional Elements . . . . .                          | 1-6  |
|     | Bus Structure . . . . .                                | 1-7  |
|     | Data Bus Description . . . . .                         | 1-7  |
|     | Data Byte Transfer Control Bus Description . . . . .   | 1-8  |
|     | General Interface Management Bus Description . . . . . | 1-9  |
|     | Device Interface Function Capability . . . . .         | 1-10 |
|     | Message Types . . . . .                                | 1-11 |
| 1-4 | 680XXB GPIB OPERATION. . . . .                         | 1-13 |
|     | Setting GPIB Operating Parameters . . . . .            | 1-13 |
|     | Selecting the Interface Language . . . . .             | 1-13 |
|     | Response to GPIB Interface Function Messages . . . . . | 1-13 |

## ***Chapter 2 - Programming with GPIB Commands***

|     |   |      |
|-----|---|------|
| 2-1 | INTRODUCTION . . . . .                      | 2-3  |
| 2-2 | COMMAND CODES . . . . .                     | 2-3  |
| 2-3 | DATA INPUT RESTRICTIONS. . . . .            | 2-6  |
| 2-4 | PARAMETER AND DATA ENTRY COMMANDS . . . . . | 2-7  |
|     | Opening a Parameter . . . . .               | 2-7  |
|     | Data Entry . . . . .                        | 2-7  |
|     | Using the SYZ Command. . . . .              | 2-12 |
| 2-5 | CW FREQUENCY COMMANDS . . . . .             | 2-13 |
| 2-6 | STEP SWEEP COMMANDS . . . . .               | 2-14 |
|     | Step Sweep Range . . . . .                  | 2-14 |
|     | Alternate Step Sweep. . . . .               | 2-15 |
|     | Sweep Triggering . . . . .                  | 2-15 |
|     | Step Sweep Select. . . . .                  | 2-17 |
|     | Special Step Sweep . . . . .                | 2-19 |
| 2-7 | FREQUENCY MARKER COMMANDS . . . . .         | 2-20 |

## ***Table of Contents (Continued)***

|      |  |      |
|------|--|------|
| 2-8  | OUTPUT POWER LEVELING COMMANDS . . .                         | 2-21 |
|      | RF Output Power Level Selection . . . . .                    | 2-21 |
|      | Alternate Sweep RF Output Power Level<br>Selection . . . . . | 2-21 |
|      | Output Power Leveling . . . . .                              | 2-21 |
|      | ALC Power Slope . . . . .                                    | 2-24 |
|      | Attenuator Decoupling . . . . .                              | 2-24 |
| 2-9  | OUTPUT COMMANDS . . . . .                                    | 2-25 |
| 2-10 | STORED SETUP COMMANDS . . . . .                              | 2-27 |
| 2-11 | SRQ AND STATUS BYTE COMMANDS . . . . .                       | 2-29 |
|      | Status Bytes. . . . .  | 2-29 |
|      | SRQ Generation. . . . .                                      | 2-29 |
| 2-12 | CONFIGURATION COMMANDS . . . . .                             | 2-34 |
| 2-13 | GROUP EXECUTE TRIGGER COMMANDS . . .                         | 2-36 |
| 2-14 | FAST-FREQUENCY-SWITCHING COMMANDS .                          | 2-37 |
| 2-15 | POWER-OFFSET-TABLE COMMANDS . . . . .                        | 2-38 |
|      | Loading the Power-Offset Table . . . . .                     | 2-38 |
| 2-16 | USER LEVEL CALIBRATION COMMANDS . . .                        | 2-41 |
|      | Editing the Table Data . . . . .                             | 2-45 |
| 2-17 | MASTER-SLAVE OPERATION COMMANDS . . .                        | 2-49 |
| 2-18 | SELF TEST COMMAND . . . . .                                  | 2-50 |
| 2-19 | MISCELLANEOUS COMMANDS . . . . .                             | 2-52 |
| 2-20 | PROGRAM ERRORS . . . . .                                     | 2-53 |
|      | Invalid-Parameter . . . . .                                  | 2-53 |
|      | Syntax . . . . .   | 2-53 |
| 2-21 | RESET PROGRAMMING AND DEFAULT<br>CONDITIONS . . . . .        | 2-54 |
| 2-22 | PROGRAMMING EXAMPLES . . . . .                               | 2-55 |

## ***Appendix A - Index of GPIB Commands***

|     |                        |     |
|-----|------------------------|-----|
| A-1 | INTRODUCTION . . . . . | A-1 |
|-----|------------------------|-----|

# **Chapter 1**

## **General GPIB Information**

### ***Table of Contents***

---

|     |  |      |
|-----|--|------|
| 1-1 | SCOPE OF MANUAL . . . . .                              | 1-3  |
|     | Electronic Manual . . . . .                            | 1-3  |
| 1-2 | INTRODUCTION . . . . .                                 | 1-3  |
| 1-3 | IEEE-488 INTERFACE BUS DESCRIPTION . . . . .           | 1-5  |
|     | Functional Elements . . . . .                          | 1-6  |
|     | Bus Structure . . . . .                                | 1-7  |
|     | Data Bus Description . . . . .                         | 1-7  |
|     | Data Byte Transfer Control Bus Description . . . . .   | 1-8  |
|     | General Interface Management Bus Description . . . . . | 1-9  |
|     | Device Interface Function Capability . . . . .         | 1-10 |
|     | Message Types . . . . .                                | 1-11 |
| 1-4 | 680XXB GPIB OPERATION . . . . .                        | 1-13 |
|     | Setting GPIB Operating Parameters . . . . .            | 1-13 |
|     | Selecting the Interface Language . . . . .             | 1-13 |
|     | Response to GPIB Interface Function Messages . . . . . | 1-13 |

# Chapter 1

## General GPIB Information

### **1-1** SCOPE OF MANUAL

This manual provides information for remote operation of the Series 680XXB Synthesized CW Generator using commands sent from an external controller via the IEEE-488 General Purpose Interface Bus (GPIB). It includes the following:

- ❑ A general description of the GPIB and the bus data transfer and control functions.
- ❑ A listing of the IEEE-488 Interface Function Messages recognized by the CW generator with a description of its response.
- ❑ A complete listing and description of all 680XXB GPIB commands (i.e., Product Specific Commands) that can be used to control CW generator operation with programming examples.

This manual is intended to be used in conjunction with the Series 680XXB Synthesized CW Generator Operation Manual, P/N 10370-10264. Refer to that manual for general information about the 680XXB, including equipment set up and front panel (manual mode) operating instructions.

#### **Electronic Manual**

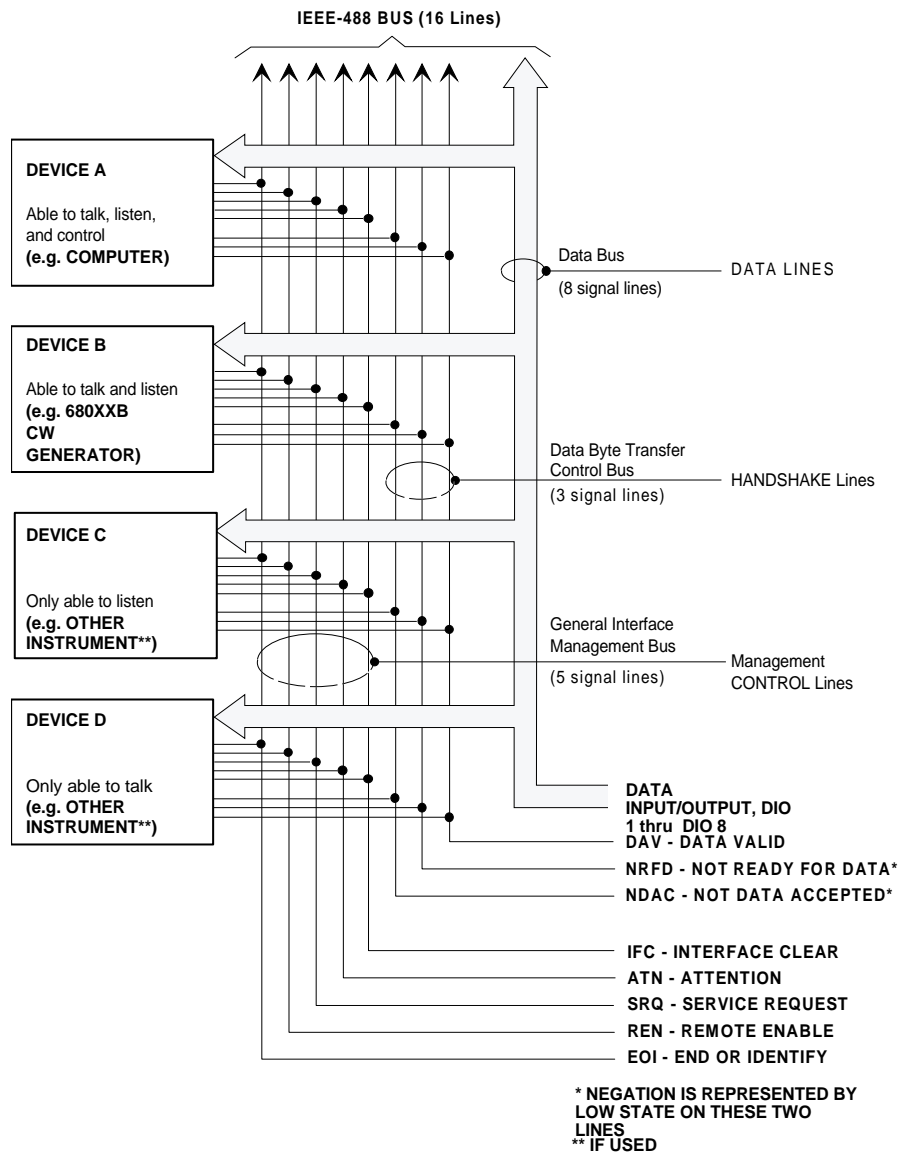
This manual is available on CD ROM as an Adobe Acrobat Portable Document Format (\*.pdf) file. The file can be viewed using Acrobat Reader, a free program that is included on the CD ROM. The file is “linked” such that the viewer can choose a topic to view from the displayed “bookmark” list and “jump” to the manual page on which the topic resides. The text can also be word-searched. Contact ANRITSU Customer Service for price and availability.

### **1-2** INTRODUCTION

This chapter provides a general description of the GPIB and the bus data transfer and control functions. It also contains a listing of the 680XXB's GPIB interface function subset capability and response to IEEE-488 interface function messages.

The GPIB information presented in this chapter is general in nature. For complete and specific information, refer to the following documents: ANSI/IEEE Std 488.1-1987 *IEEE Standard Digital Interface for Programmable Instrumentation* and ANSI/IEEE Std 488.2-1987 *IEEE Standard Codes, Formats, Protocols and Common Commands*. These documents precisely define the total specification of the mechanical and electrical interface, and of the data transfer and control protocols.





**Figure 1-1.** Interface Connections and GPIB Bus Structure

**1-3 IEEE-488 INTERFACE  
BUS DESCRIPTION**

The IEEE-488 General Purpose Interface Bus (GPIB) is an instrumentation interface for integrating instruments, computers, printers, plotters, and other measurement devices into systems. The GPIB uses 16 signal lines to effect transfer of information between all devices connected on the bus.

The following requirements and restrictions apply to the GPIB.

- ❑ No more than 15 devices can be interconnected by one contiguous bus; however, an instrumentation system may contain more than one interface bus.
- ❑ The maximum total cumulative cable length for one interface bus may not exceed twice the number of devices connected (in meters), or 20 meters—whichever is less.
- ❑ A maximum data rate of 1 Mb/s across the interface on any signal line.
- ❑ Each device on the interface bus must have a unique address, ranging from 00 to 30.

The devices on the GPIB are connected in parallel, as shown in Figure 1-1. The interface consists of 16 signal lines and 8 ground lines in a shielded cable. Eight of the signal lines are the data lines, DIO 1 thru DIO 8. These data lines carry messages (data and commands), one byte at a time, among the GPIB devices. Three of the remaining lines are the handshake lines that control the transfer of message bytes between devices. The five remaining signal lines are referred to as interface management lines.

The following paragraphs provide an overview of the GPIB including a description of the functional elements, bus structure, bus data transfer process, interface management bus, device interface function requirements, and message types.

***Functional  
Elements***

Effective communications between devices on the GPIB requires three functional elements; a *talker*, a *listener*, and a *controller*. Each device on the GPIB is categorized as one of these elements depending on its current interface function and capabilities.

***Talker***

A talker is a device capable of sending device-dependent data to another device on the bus when addressed to talk. Only one GPIB device at a time can be an active talker.

***Listener***

A listener is a device capable of receiving device-dependent data from another device on the bus when addressed to listen. Any number of GPIB devices can be listeners simultaneously.

***Controller***

A controller is a device, usually a computer, capable of managing the operation of the GPIB. Only one GPIB device at a time can be an active controller. The active controller manages the transfer of device-dependent data between GPIB devices by designating who will talk and who will listen.

***System Controller***

The system controller is the device that always retains ultimate control of the GPIB. When the system is first powered-up, the system controller is the active controller and manages the GPIB. The system controller can pass control to a device, making it the new active controller. The new active controller, in turn, may pass control on to yet another device. Even if it is not the active controller, the system controller maintains control of the Interface Clear (IFC) and Remote Enable (REN) interface management lines and can thus take control of the GPIB at anytime.

***Bus  
Structure***

The GPIB uses 16 signal lines to carry data and commands between the devices connected to the bus. The interface signal lines are organized into three functional groups.

- ❑ Data Bus (8 lines)
- ❑ Data Byte Transfer Control Bus (3 lines)
- ❑ General Interface Management Bus (5 lines)

The signal lines in each of the three groups are designated according to function. Table 1-1 lists these designations.

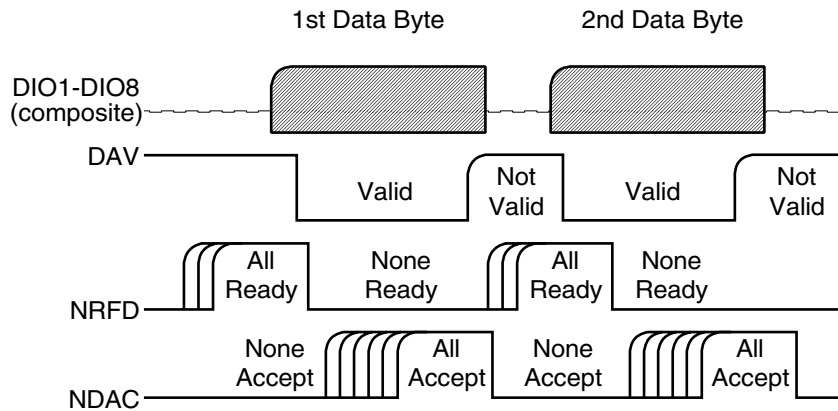
**Table 1-1.** *Interface Bus Signal Line Designations*

| Bus Type                         | Signal Line Name                | Function  |
|----------------------------------|---------------------------------|---|
| Data Bus                         | DIO1–DIO8                       | Data Input/Output, 1 thru 8   |
| Data Byte Transfer Control Bus   | DAV<br>NRFD<br>NDAC             | Data Available<br>Not Ready For Data<br>Not Data Accepted                           |
| General Interface Management Bus | ATN<br>IFC<br>SRQ<br>REN<br>EOI | Attention<br>Interface Clear<br>Service Request<br>Remote Enable<br>End Or Identify |

***Data Bus  
Description***

The data bus is the conduit for the transfer of data and commands between the devices on the GPIB. It contains eight bi-directional, active-low signal lines—DIO 1 thru DIO 8. Data and commands are transferred over the data bus in byte-serial, bit-parallel form. This means that one byte of data (eight bits) is transferred over the bus at a time. DIO 1 represents the least-significant bit (LSB) in this byte and DIO 8 represents the most-significant bit (MSB). Bytes of data are normally formatted in seven-bit ASCII (American Standard Code for Information Interchange) code. The eighth (parity) bit is not used.

Each byte placed on the data bus represents either a command or a data byte. If the Attention (ATN) interface management line is TRUE while the data is transferred, then the data bus is carrying a bus command which is to be received by every GPIB device. If ATN is FALSE, then a data byte is being transferred and only the active listeners will receive that byte.



**Figure 1-2.** Typical GPIB Handshake Operation

**Data Byte  
Transfer  
Control Bus  
Description**

Control of the transfer of each byte of data on the data bus is accomplished by a technique called the “three-wire handshake”, which involves the three signal lines of the Data Byte Transfer Control Bus. This technique forces data transfers at the speed of the slowest listener, which ensures data integrity in multiple listener transfers. One line (DAV) is controlled by the talker, while the other two (NRFD and NDAC) are wired-OR lines shared by all active listeners. The handshake lines, like the other GPIB lines, are active low. The technique is described briefly in the following paragraphs and is depicted in Figure 1-2. For further information, refer to ANSI/IEEE Std 488.1.

**DAV (Data Valid)**

This line is controlled by the active talker. Before sending any data, the talker verifies that NDAC is TRUE (active low) which indicates that all listeners have accepted the previous data byte. The talker then places a byte on the data lines and waits until NRFD is FALSE (high) which indicates that all addressed listeners are ready to accept the information. When both NRFD and NDAC are in the proper state, the talker sets the DAV line TRUE (active low) to indicate that the data on the bus is valid (stable).

**NRFD (Not Ready For Data)**

This line is used by the listeners to inform the talker when they are ready to accept new data. The talker must wait for each listener to set the NRFD

line FALSE (high) which they will do at their own rate. This assures that all devices that are to accept the data are ready to receive it.

***NDAC (Not Data Accepted)***

This line is also controlled by the listeners and is used to inform the talker that each device addressed to listen has accepted the data. Each device releases NDAC at its own rate, but NDAC will not go FALSE (high) until the slowest listener has accepted the data byte.

***General  
Interface  
Management  
Bus  
Description***

The general interface management bus is a group of five signal lines used to manage the flow of information across the GPIB. A description of the function of each of the individual control lines is provided below.

***ATN (Attention)***

The active controller uses the ATN line to define whether the information on the data bus is a command or is data. When ATN is TRUE (low), the bus is in the command mode and the data lines carry bus commands. When ATN is FALSE (high), the bus is in the data mode and the data lines carry device-dependent instructions or data.

***EOI (End or Identify)***

The EOI line is used to indicate the last byte of a multibyte data transfer. The talker sets the EOI line TRUE during the last data byte.

The active controller also uses the EOI line in conjunction with the ATN line to initiate a parallel poll sequence.

***IFC (Interface Clear)***

Only the system controller uses this line. When IFC is TRUE (low), all devices on the bus are placed in a known, quiescent state (unaddressed to talk, unaddressed to listen, and service request idle).

***REN (Remote Enable)***

Only the system controller uses this line. When REN is set TRUE (low), the bus is in the remote mode and devices are addressed either to listen or to talk. When the bus is in remote and a device is addressed, it receives instructions from the GPIB rather than from its front panel. When REN is set FALSE (high), the bus and all devices return to local operation.

***SRQ (Service Request)***

The SRQ line is set TRUE (low) by any device requesting service by the active controller.

***Device  
Interface  
Function  
Capability***

An interface function is the GPIB system element which provides the basic operational facility through which a device can receive, process, and send messages. Each specific interface function may only send or receive a limited set of messages within particular classes of messages. As a result, a set of interface functions is necessary to achieve complete communications among devices on the GPIB. ANSI/IEEE Std 488.1 defines each of the interface functions along with its specific protocol.

ANSI/IEEE Std 488.2 specifies the minimum set of IEEE-488.1 interface capabilities that each GPIB device must have. This minimum set of interface functions assures that the device is able to send and receive data, request service, and respond to a device clear message. Table 1-2 lists the interface function capability of the series 680XXB CW generator.

**Table 1-2.** 680XXB Interface Function Capability

| Function Identifier | Function                      | 680XXB Capability   |
|---------------------|-------------------------------|---|
| AH1                 | Acceptor Handshake            | Complete Capability   |
| SH1                 | Source Handshake              | Complete Capability   |
| T6                  | Talker                        | No Talk Only (TON)  |
| L4                  | Listener                      | No Listen Only (LON)  |
| SR1                 | Service Request               | Complete Capability   |
| RL1                 | Remote/Local                  | Complete Capability   |
| PP1                 | Parallel Poll                 | Complete Capability   |
| DC1                 | Device Clear                  | Complete Capability   |
| DT1                 | Device Trigger                | Complete Capability   |
| C0, C1, C2, C3, C28 | Controller Capability Options | C0, No Capability;<br>C1, System Controller;<br>C2, Send IFC and Take Charge;<br>C3, Send REN;<br>C28, Send IF Messages |
| E2                  | Tri-State Drivers             | Three-state bus drivers   |

***Message  
Types***

There are three types of information transmitted over the GPIB—interface function messages, device-specific commands, and data and instrument status messages.

***Interface Function Messages***

The controller manages the flow of information on the GPIB using interface function messages, usually called *commands* or *command messages*. Interface function messages perform such functions as initializing the bus, addressing and unaddressing devices, and setting device modes for remote or local operation.

There are two types of commands—multiline and uniline. Multiline commands are bytes sent by the active controller over the data bus (DIO1-DIO8) with ATN set TRUE. Uniline commands are signals carried by the individual interface management lines.

The user generally has control over these commands; however, the extent of user control depends on the implementation and varies with the specific GPIB interface hardware and software used with the external controller.

***Device-Specific Commands***

These commands are keywords or mnemonic codes sent by the external controller to control the setup and operation of the addressed device or instrument. The commands are normally unique to a particular instrument or class of instruments and are described in its documentation.

Device-specific commands are transmitted over the data bus of the GPIB to the device in the form of ASCII strings containing one or more keywords or codes. They are decoded by the device's *internal controller* and cause the various instrument functions to be performed.

***Data and Instrument Status Messages***

These messages are sent by the device to the external controller via the GPIB. They contain measurement results, instrument status, or data files that the device transmits over the data bus in response to specific requests from the external controller. The contents of these messages are instrument specific and may be in the form of ASCII strings or binary data.



In some cases data messages will be transmitted from the external controller to the device. For example, messages to load calibration data.

An SRQ (service request) is an interface function message sent *from the device* to the external controller to request service from the controller, usually due to some predetermined status condition or error. To send this message, the device sets the SRQ line of the General Interface Management Bus true, then sends a status byte on the data bus lines.

An SRQ interface function message is also sent by the device in response to a serial poll message from the controller, or upon receiving an Output Status Byte(s) command from the controller. The protocols associated with the SRQ functions are defined in the ANSI/IEEE Std 488.2 document.

The manner in which interface function messages and device-specific commands are invoked in programs is implementation specific for the GPIB interface used with the external controller. Even though both message types are represented by mnemonics, they are implemented and used in different ways.

Normally, the interface function messages are sent automatically by the GPIB driver software in response to invocation of a software function. For example, to send the IFC (Interface Clear) interface function message, one would call the `ibsic` function of the National Instruments software driver. On the other hand, the command `*RST` (Reset) is sent in a command string to the addressed device. In the case of the National Instruments example, this would be done by using the `ibwrt` function call.

**1-4 680XXB GPIB  
OPERATION**

All Series 680XXB Synthesized CW Generator functions, settings, and operating modes (except for power on/standby) are controllable using commands sent from an external controller via the GPIB. When in the remote (GPIB) mode, the CW generator functions both as a listener and a talker. The GPIB interface function capability of the 680XXB is listed in Table 1-2 (page 1-10).

***Setting GPIB  
Operating  
Parameters***

The 680XXB leaves the factory with the GPIB address value set to 5 and the data delimiting terminator set to carriage return and line feed (CR/LF). A different address value can be entered from the front panel using the Configure GPIB menu. Using this same menu, the data delimiting terminator can be changed to carriage return (CR) only. Refer to Chapter 2 of the Series 680XXB Synthesized CW Generator Operation Manual for the procedure.

***Selecting the  
Interface  
Language***

Series 680XXB Synthesized CW Generators with Option 19 can be remotely operated using one of two external interface languages—Native or SCPI. The Native interface language uses a set of 680XXB GPIB Product-Specific commands to control the instrument; the SCPI interface language uses a set of the Standard Commands for Programmable Instruments commands to control the unit. Selecting which of these external interface languages is to be used can be done from the front panel using the Configure GPIB menu. Refer to Chapter 2 of the Series 680XXB Synthesized CW Generators Operation Manual for the procedure.

***Response to  
GPIB  
Interface  
Function  
Messages***

Table 1-3 (page 1-14) lists the GPIB Interface Function Messages that the 680XXB will recognize and respond to. With the exception of the Device Clear and Selected Device Clear messages, these messages affect only the operation of the 680XXB GPIB interface. The 680XXB response for each message is indicated.

Interface function messages are transmitted on the GPIB data lines and interface management lines as either unaddressed or addressed commands. The manner in which these messages are invoked in programs is implementation dependent. For programming information, refer to the documentation included with the GPIB Interface for the external controller used.

**Table 1-3.** *680XXB Response to GPIB Interface Function Messages*

| <b>Interface Function Message</b> | <b>Addressed Command</b> | <b>680XXB Response</b>  |
|-----------------------------------|--------------------------|---|
| Device Clear (DCL)                | No                       | Resets the 680XXB to its default state. (Equivalent to sending the *RST command.)   |
| Selected Device Clear (SDC)       | Yes                      |   |
| Go To Local (GTL)                 | Yes                      | Returns the 680XXB to local (front panel) control.  |
| Group Execute Trigger (GET)       | Yes                      | Executes a string of commands, if programmed.   |
| Interface Clear (IFC)             | No                       | Stops the 680XXB GPIB interface from listening or talking. (The front panel controls are not cleared.)  |
| Local Lockout (LLO)               | No                       | Disables the front panel menu RETURN TO LOCAL soft-key.   |
| Remote Enable (REN)               | No                       | Places the 680XXB under remote (GPIB) control when it has been addressed to listen.   |
| Serial-Poll Enable (SPE)          | No                       | Outputs the serial-poll status byte.  |
| Serial-Poll Disable (SPD)         | No                       | Disables the serial-poll function.  |
| Parallel-Poll Configure (PPC)     | Yes                      | Responds to a parallel-poll message (PPOLL) by setting assigned data bus line to the logical state (1,0) that indicates its correct SRQ status. |
| Parallel-Poll Unconfigure (PPU)   | No                       | Disables the parallel-poll function.  |

# **Chapter 2**

## **Programming with GPIB Commands**

### **Table of Contents**

---

|      |   |      |
|------|---|------|
| 2-1  | INTRODUCTION . . . . .                          | 2-3  |
| 2-2  | COMMAND CODES . . . . .                         | 2-3  |
| 2-3  | DATA INPUT RESTRICTIONS. . . . .                | 2-6  |
| 2-4  | PARAMETER AND DATA ENTRY COMMANDS . . . . .     | 2-7  |
|      | Opening a Parameter . . . . .                   | 2-7  |
|      | Data Entry . . . . .                            | 2-7  |
|      | Using the SYZ Command. . . . .                  | 2-12 |
| 2-5  | CW FREQUENCY COMMANDS . . . . .                 | 2-13 |
| 2-6  | STEP SWEEP COMMANDS . . . . .                   | 2-14 |
|      | Step Sweep Range . . . . .                      | 2-14 |
|      | Alternate Step Sweep. . . . .                   | 2-15 |
|      | Sweep Triggering . . . . .                      | 2-15 |
|      | Step Sweep Select. . . . .                      | 2-17 |
|      | Special Step Sweep . . . . .                    | 2-19 |
| 2-7  | FREQUENCY MARKER COMMANDS . . . . .             | 2-20 |
| 2-8  | OUTPUT POWER LEVELING COMMANDS . . . . .        | 2-21 |
|      | RF Output Power Level Selection . . . . .       | 2-21 |
|      | Alternate Sweep RF Output Power Level Selection | 2-21 |
|      | Output Power Leveling. . . . .                  | 2-21 |
|      | ALC Power Slope . . . . .                       | 2-24 |
|      | Attenuator Decoupling . . . . .                 | 2-24 |
| 2-9  | OUTPUT COMMANDS . . . . .                       | 2-25 |
| 2-10 | STORED SETUP COMMANDS. . . . .                  | 2-27 |
| 2-11 | SRQ AND STATUS BYTE COMMANDS . . . . .          | 2-29 |
|      | Status Bytes. . . . .                           | 2-29 |

**Table of Contents (Continued)**

|      |  |      |
|------|--|------|
|      | SRQ Generation. . . . .                                | 2-29 |
| 2-12 | CONFIGURATION COMMANDS. . . . .                        | 2-34 |
| 2-13 | GROUP EXECUTE TRIGGER COMMANDS . . . .                 | 2-35 |
| 2-14 | FAST-FREQUENCY-SWITCHING COMMANDS .                    | 2-36 |
| 2-15 | POWER-OFFSET-TABLE COMMANDS . . . . .                  | 2-37 |
|      | Loading the Power-Offset Table . . . . .               | 2-37 |
| 2-16 | USER LEVEL CALIBRATION COMMANDS . . . .                | 2-40 |
|      | Editing the Table Data . . . . .                       | 2-44 |
| 2-17 | MASTER-SLAVE OPERATION COMMANDS . . . .                | 2-48 |
| 2-18 | SELF TEST COMMANDS. . . . .                            | 2-49 |
| 2-19 | MISCELLANEOUS COMMANDS . . . . .                       | 2-51 |
| 2-20 | PROGRAM ERRORS . . . . .                               | 2-52 |
|      | Invalid-Parameter . . . . .                            | 2-52 |
|      | Syntax . . . . .                                       | 2-52 |
| 2-21 | RESET PROGRAM-MING AND DEFAULT<br>CONDITIONS . . . . . | 2-53 |
| 2-22 | PROGRAMMING EXAMPLES . . . . .                         | 2-54 |

# Chapter 2

## Programming with GPIB Commands

### **2-1** INTRODUCTION

This chapter provides information for remote operation of the Series 680XXB Synthesized CW Generator via the GPIB using 680XXB GPIB commands. All GPIB Product-Specific commands that are accepted and implemented by the 680XXB are listed and described by function. Sample programs showing usage of the commands are also included.

### **2-2** COMMAND CODES

There are over two hundred and fifty GPIB Product-Specific commands that are accepted and implemented by the 680XXB. These GPIB commands allow the user to program all front panel and menu functions (except for power on/standby). Each GPIB command is a two- or three-character mnemonic code that represents an instrument command or parameter; for example: RST (reset).

Table 2-1, beginning on page 2-4, is a listing of all 680XXB GPIB command mnemonic codes grouped into functional categories. The listing for each category includes references to the paragraph and page number in this chapter where a complete description of that group of commands can be found.

#### **NOTE**

A quick way to determine the function of any of the GPIB command codes listed in Table 2-1 is to look up the command code of interest in Appendix A of this manual. Appendix A is an alphabetical index of all 680XXB GPIB command mnemonic codes. A brief description of the function of each command is also included.

**Table 2-1.** 680XXB GPIB Command Codes Listed by Function (1 of 2)

| <b>GPIB Command Group Function</b>             | <b>Command Codes</b>   | <b>Para.</b> | <b>Page</b> |
|--|--|--------------|-------------|
| Parameter Entry Commands                       | F0, F1, F2, F3, F4, F5, F6, F7, F8, F9, M0, M1, M2, M3, M4, M5, M6, M7, M8, M9, XL0, XL1, XL2, XL3, XL4, XL5, XL6, XL7, XL8, XL9, DLF, DFF, DFM, SLF0, SLF1, SLF2, SLF3, SLF4, SLF5, SLF6, SLF7, SFL8, SLF9, SLM0, SLM1, SLM2, SLM3, SLM4, SLM5, SLM6, SLM7, SLM8, SLM9, SLDF, SDT, SNS, SWT, LOS, PDT, PNS, PVT, SLP, EGI, SOF, SLV, SLL1, SLL2, ADD, FRS, SYZ, UP, DN, CLO | 2-4          | 2-7         |
| Data Entry/<br>Data Terminator<br>Commands     | 0 thru 9, -, ., ADR, CLR, DB, DM, GH, MH, KH, HZ, SEC, MS, US, NS, PCT, GV, MV, KV, DV, PCV, SPS, TMS  | 2-4          | 2-10        |
| CW Frequency<br>Commands                       | CF0, CF1, CF2, CF3, CF4, CF5, CF6, CF7, CF8, CF9, CM0, CM1, CM2, CM3, CM4, CM5, CM6, CM7, CM8, CM9, SQF, SQU, SQD, ACW   | 2-5          | 2-13        |
| Step Sweep<br>Commands                         | SF1, SF3, FUL, DF0, DF1, DF5, DF6, AFU, AF1, AF3, AD1, AD5, AD6, AUT, EXT, TRG, TRS, RSS, SSP, MAN, DU1, DU0, TSS, SP1, SP0  | 2-6          | 2-14        |
| Frequency Marker<br>Commands                   | ME1, ME0, MK0, VM1   | 2-7          | 2-20        |
| Power Leveling<br>Commands                     | L0, L1, L2, L3, L4, L5, L6, L7, L8, L9, AL0, AL1, AL2, AL3, AL4, AL5, AL6, AL7, AL8, AL9, RF1, RF0, LO1, LO0, IL1, DL1, PL1, ELF, ELR, LV0, LSP, AT0, AT1, ATT(xx), SL0, SL1, EGO  | 2-8          | 2-21        |
| Output Commands                                | *IDN?, OI, OFL, OFH, OF0, OF1, OF2, OF3, OF4, OF5, OF6, OF7, OF8, OF9, OM0, OM1, OM2, OM3, OM4, OM5, OM6, OM7, OM8, OM9, OL0, OL1, OL2, OL3, OL4, OL5, OL6, OL7, OL8, OL9, OLO, ODF, OPD, OPS, OSD, OSS, OST, OVN, OWT, OSE, OEM, OES, OSB, OSM, OSR   | 2-9          | 2-25        |
| Stored Setup<br>Commands                       | SAF, SAM, SM, SSN(M1-9), RCF, RCM, RSN(M1-9)   | 2-10         | 2-27        |
| Service Request<br>and Status Byte<br>Commands | ES1, ES0, FB1, FB0, LE1, LE0, MB0, MB1, MB2, PE1, PE0, SB1, SB0, SE1, SE0, SQ1, SQ0, UL1, UL0, LS1, LS0, EL1, EL0, I11, I10, CSB   | 2-11         | 2-29        |

**Table 2-1.** 680XXB GPIB Command Codes Listed by Function (2 of 2)

| <b>GPIB Command<br/>Group Function</b>     | <b>Command Codes</b>  | <b>Para.</b> | <b>Page</b> |
|--|---|--------------|-------------|
| Configuration<br>Commands                  | BPN, BPP, FRS, PPO, PPC, RC0, RC1,<br>RT0, RT1, RO0, RO1, RR0, RR1, TR0,<br>TR1 | 2-12         | 2-34        |
| Group Execute<br>Trigger (GET)<br>Commands | GTC, GTD, GTF, GTL, GTO, GTS, GTT,<br>GTU, Y                                    | 2-13         | 2-36        |
| Fast-Frequency-<br>Switching<br>Commands   | ZL(X000-999), ZEL, ZS(X000-999)   | 2-14         | 2-37        |
| Power-Offset-<br>Table Commands            | PT0, PT1, PTC, PTL  | 2-15         | 2-38        |
| User Level<br>Calibration<br>Commands      | LU0, LU1, LU2, LU3, LU4, LU5, LUS, LUR  | 2-16         | 2-41        |
| Master-Slave<br>Operation<br>Commands      | S0, S1  | 2-17         | 2-49        |
| Self Test<br>Commands                      | TST   | 2-18         | 2-50        |
| Miscellaneous<br>Commands                  | ADD, CS0, CS1, DS0, DS1, RL, RST, SNR   | 2-19         | 2-52        |



**2-3 DATA INPUT  
RESTRICTIONS**

The 680XXB CW generator does *not* accept parameter or data entries in an exponential or scientific notation format. The accepted data formats are as follows:

- A decimal or integer format for entering parameters and data.
- A binary-byte format for entering the status byte mask commands (para. 2-11), the RCF and RCM stored-setup commands (para. 2-10), the power-offset-table commands (para. 2-15), and the LUR user level calibration command (para. 2-16).

**Programming Note:** The CW generator only recognizes the following 65 characters:

- The 52 upper- and lower-case alphabetic characters. (The 680XXB accepts both upper- and lower-case characters without distinguishing between the cases).
- The minus sign (-).
- The comma (,).
- The decimal point (.
- The numerals between 0 and 9.

All characters other than the 65 listed above are ignored and can be interspersed between meaningful characters without ill effect. This use of other characters can improve readability. For example, the two command strings below are valid and interchangeable.

**"F12.754GHF27.792GHSF1SWPMKOL12DM"**

**"F1=2.754 GH, F2=7.792 GH, SF1, SWP, MKO, L1=2 DM"**

**2-4** **PARAMETER AND DATA  
ENTRY COMMANDS**

Table 2-2 lists the command mnemonic codes that open parameters for data entry. The table also provides the range of values permitted for each parameter and the data terminator mnemonic codes for each. Tables 2-3 and 2-4 (page 2-11) list the data entry and data terminator command mnemonic codes.

**Opening a  
Parameter**

All of the commands listed in Table 2-2 open a parameter for data entry. Once opened, a parameter remains open until one of the following occurs:

- ❑ Another parameter is opened.
- ❑ A function other than video markers or output power leveling is commanded.
- ❑ The CLO (close open parameter) command is received.

**Data Entry**

When a parameter is open for data entry, its value can be changed as follows:

- ❑ By sending a numeric value followed by the appropriate terminator code.
- ❑ By incrementing or decrementing its value using an associated step size.

**NOTE**

An appropriate data terminator *must* be used to terminate a numeric-parameter entry, and it *must* immediately follow the numeric value. If it does not, a parameter entry error will result.

The parameter and data entry commands do not affect the CW generator's output unless the parameter being changed is also the current output parameter. The commands, therefore, may be used to change the preset values of parameters without altering the 680XXB's output.

**Example:** Assume that the 680XXB is executing an F3-F4 sweep from 3 GHz to 10 GHz. Changing the value of F1 to 3 GHz with the command string "F1 3 GH" does not affect the current output of the CW generator. However, changing the value of F4 with the command string "F4 16.01 GH" alters the output of the 680XXB because it changes the end point of the F3-F4 sweep to 16.01 GHz.

**Table 2-2.** *Parameter Entry Commands (1 of 3)*

| <b>MNEMONIC<br/>CODE</b> | <b>PARAMETER</b>                | <b>VALUES</b>  | <b>TERMINATOR</b> |
|--------------------------|---------------------------------|--|-------------------|
| F0                       | Opens the F0 parameter          | Dependent on the<br>frequency range of<br>the instrument   | GH                |
| F1                       | Opens the F1 parameter          |  | MH                |
| F2                       | Opens the F2 parameter          |  | KH                |
| F3                       | Opens the F3 parameter          |  | HZ                |
| F4                       | Opens the F4 parameter          |  |                   |
| F5                       | Opens the F5 parameter          |  |                   |
| F6                       | Opens the F6 parameter          |  |                   |
| F7                       | Opens the F7 parameter          |  |                   |
| F8                       | Opens the F8 parameter          |  |                   |
| F9                       | Opens the F9 parameter          |  |                   |
| M0                       | Opens the M0 parameter          | Dependent on the<br>frequency range of<br>the instrument   | GH                |
| M1                       | Opens the M1 parameter          |  | MH                |
| M2                       | Opens the M2 parameter          |  | KH                |
| M3                       | Opens the M3 parameter          |  | HZ                |
| M4                       | Opens the M4 parameter          |  |                   |
| M5                       | Opens the M5 parameter          |  |                   |
| M6                       | Opens the M6 parameter          |  |                   |
| M7                       | Opens the M7 parameter          |  |                   |
| M8                       | Opens the M8 parameter          |  |                   |
| M9                       | Opens the M9 parameter          |  |                   |
| XL0                      | Opens the L0 parameter          | Dependent on the<br>power level range<br>of the instrument | DM                |
| XL1                      | Opens the L1 parameter          |  |                   |
| XL2                      | Opens the L2 parameter          |  |                   |
| XL3                      | Opens the L3 parameter          |  |                   |
| XL4                      | Opens the L4 parameter          |  |                   |
| XL5                      | Opens the L5 parameter          |  |                   |
| XL6                      | Opens the L6 parameter          |  |                   |
| XL7                      | Opens the L7 parameter          |  |                   |
| XL8                      | Opens the L8 parameter          |  |                   |
| XL9                      | Opens the L9 parameter          |  |                   |
| DLF                      | Opens the $\Delta F$ parameter  | Dependent on the<br>frequency range of<br>the instrument   | GH                |
| DFF                      | Opens the $\Delta F$ parameter  |  | MH                |
| DFM                      | Opens the $\Delta F$ parameter  |  | KH                |
|                          |                                 |  | HZ                |
|                          | <i>Slave 68XXXB Frequencies</i> |  |                   |
| SLF0                     | Opens the F0 parameter          | Dependent on the<br>frequency range of<br>the instrument   | GH                |
| SLF1                     | Opens the F1 parameter          |  | MH                |
| SLF2                     | Opens the F2 parameter          |  | KH                |
| SLF3                     | Opens the F3 parameter          |  | HZ                |
| SLF4                     | Opens the F4 parameter          |  |                   |
| SLF5                     | Opens the F5 parameter          |  |                   |
| SLF6                     | Opens the F6 parameter          |  |                   |
| SLF7                     | Opens the F7 parameter          |  |                   |
| SLF8                     | Opens the F8 parameter          |  |                   |
| SLF9                     | Opens the F9 parameter          |  |                   |

**Table 2-2.** *Parameter Entry Commands (2 of 3)*

| <b>MNEMONIC<br/>CODE</b> | <b>PARAMETER</b>   | <b>VALUES</b>  | <b>TERMINATOR</b>    |
|--------------------------|--|--|----------------------|
|                          | <i>Slave 68XXB Frequencies</i>   |  |                      |
| SLM0                     | Opens the M0 parameter   | Dependent on the<br>frequency range of<br>the instrument | GH                   |
| SLM1                     | Opens the M1 parameter   |  | MH                   |
| SLM2                     | Opens the M2 parameter   |  | KH                   |
| SLM3                     | Opens the M3 parameter   |  | HZ                   |
| SLM4                     | Opens the M4 parameter   |  |                      |
| SLM5                     | Opens the M5 parameter   |  |                      |
| SLM6                     | Opens the M6 parameter   |  |                      |
| SLM7                     | Opens the M7 parameter   |  |                      |
| SLM8                     | Opens the M8 parameter   |  |                      |
| SLM9                     | Opens the M9 parameter   |  |                      |
| SLDF                     | Opens the $\Delta F$ parameter<br>for the slave 68XXXB                                     | Dependent on the<br>frequency range of<br>the instrument | GH<br>MH<br>KH<br>HZ |
| SDT                      | Opens the step sweep<br>dwell time parameter   | 1 ms to 99 sec   | MS<br>SEC            |
| SNS                      | Opens the step sweep<br>number of steps parameter  | 1 to 10,000  | SPS                  |
| SWT                      | Opens the CW ramp time<br>parameter  | 30 ms to 99 sec  | MS<br>SEC            |
| LOS                      | Opens the level offset<br>parameter  | +100 dB to<br>-100 dB                                    | DB                   |
| PDT                      | Opens the power sweep<br>dwell time parameter  | 1 ms to 99 sec   | MS<br>SEC            |
| PNS                      | Opens the power sweep<br>number of steps parameter   | 1 to 10,000  | SPS                  |
| PVT                      | Opens the ALC power<br>slope pivot point frequency<br>parameter                            | Dependent on the<br>frequency range of<br>the instrument | GH<br>MH<br>KH<br>HZ |
| SLP                      | Opens the ALC power<br>slope value parameter   | 0 to 255   | SPS                  |
| EGI                      | Opens the Reference Level<br>DAC setting parameter (in<br>external power leveling<br>mode) | 0 to 255   | SPS                  |

**Table 2-2.** *Parameter Entry Commands (3 of 3)*

| <b>MNEMONIC<br/>CODE</b> | <b>PARAMETER</b>  | <b>VALUES</b>  | <b>TERMINATOR</b>    |
|--------------------------|---|--|----------------------|
| SOF                      | Opens the frequency offset parameter for the slave 68XXXB (in a 360B VNA configuration) | Dependent on the frequency range of the instrument   | GH<br>MH<br>KH<br>HZ |
| SLV, SLL1                | Opens the main power level parameter (L1) for the slave 68XXXB                          | Dependent on the power level range of the instrument | DM                   |
| SLL2                     | Opens the alternate sweep power level parameter (L2) for the slave 68XXXB               | Dependent on the power level range of the instrument | DM                   |
| ADD                      | Opens the GPIB address parameter  | 1 to 30  | ADR                  |
| FRS                      | Opens the frequency scaling reference multiplier parameter                              | 0.1 to 14  | TMS                  |
| SYZ                      | Opens the step-size parameter for updating  | Dependent on the open parameter                      | N/A                  |
| UP                       | Increments the open parameter by the step size  | N/A  | N/A                  |
| DN                       | Decrements the open parameter by the step size  | N/A  | N/A                  |
| CLO                      | Closes the previously opened parameter  | N/A  | N/A                  |

**Table 2-3.** *Data Entry Commands*

| <b>MNEMONIC<br/>CODE</b>        | <b>DESCRIPTION</b>                   |
|---------------------------------|--------------------------------------|
| 0, 1, 2, 3, 4,<br>5, 6, 7, 8, 9 | Numerals for parameter value entries |
| –                               | Change sign of input                 |
| .                               | Decimal point                        |
| CLR                             | Clear data entry                     |

**Table 2-4.** *Data Terminator Codes*

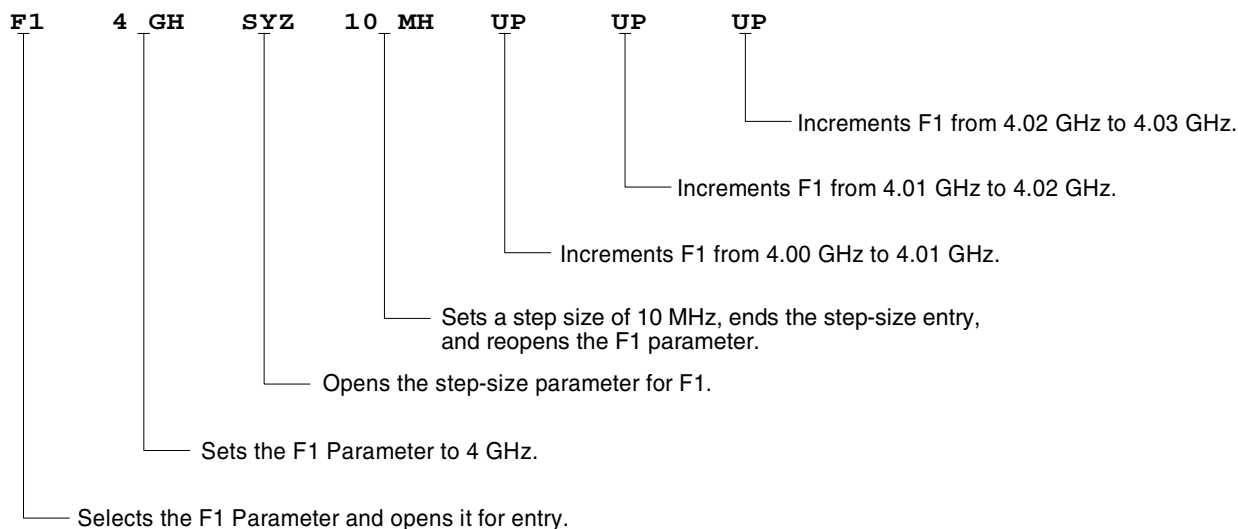
| <b>MNEMONIC<br/>CODE</b> | <b>DESCRIPTION</b>      |
|--------------------------|-------------------------|
| ADR                      | GPIB Address            |
| DB                       | Decibels (dB)           |
| DM                       | dBm                     |
| GH                       | GHz                     |
| MH                       | MHz                     |
| KH                       | kHz                     |
| HZ                       | Hertz (Hz)              |
| SEC                      | Seconds                 |
| MS                       | Milliseconds (ms)       |
| US                       | Microseconds ( $\mu$ s) |
| NS                       | Nanoseconds (ns)        |
| PCT                      | Percent (%)             |
| GV                       | GHz per volt (GHz/V)    |
| MV                       | MHz per volt (MHz/V)    |
| KV                       | kHz per volt (kHz/V)    |
| DV                       | Decibel per volt (dB/V) |
| PCV                      | Percent per volt (%/V)  |
| SPS                      | Steps                   |
| TMS                      | Times                   |

***Using the  
SYZ  
Command***

Each 680XXB parameter has an associated step size that can be used to increment or decrement its value. Parameters that have common units share a common step size. For example, the frequency parameters (F0-F9, M0-M9, and  $\Delta F$ ) have a common step size as do the power level parameters (XL0-XL9, L0-L9, and Level Offset). Other parameters, such as step sweep dwell time, have individual step sizes.

To set the step size for a parameter, first send the command code to open the parameter, then send the SYZ command. Now set the step size by sending a numeric string with the proper terminator. When the terminator is received, the step size is accepted and the original parameter is again open for entry.

Figure 2-1 shows how the SYZ command can be used to increment a parameter. In this example, the F1 frequency parameter is set to 4 GHz, the step size is set to 10 MHz, and F1 frequency is incremented three times by the value of the step size.



**Figure 2-1.** Using the SYZ (Step Size) Command

**2-5 CW FREQUENCY  
COMMANDS**

Table 2-5 lists the CW frequency command mnemonic codes. These commands call up each of the 20 preset (or previously set) CW frequencies. Each command causes its associated CW frequency to be output and opens that frequency's parameter for data entry.

The command, SQF, accesses the preset frequencies in sequential order—that is, F0 to F9 and M0 to M9.

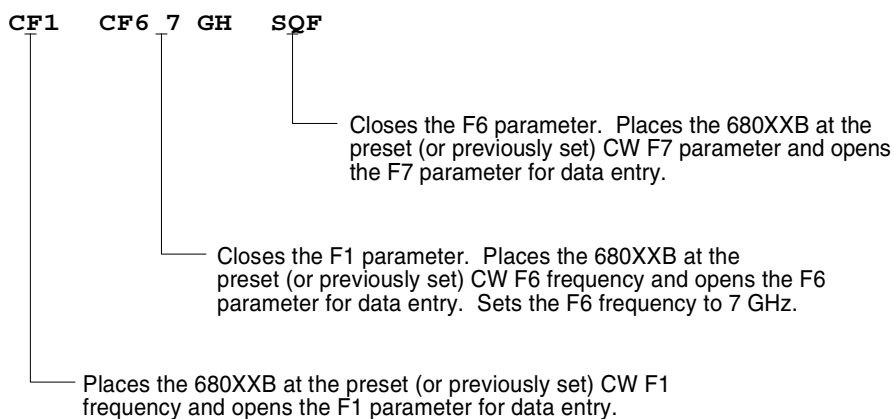
**Table 2-5.** *CW Frequency Commands*

| <b>MNEMONIC<br/>CODE</b> | <b>FUNCTION</b>                                  | <b>OPENS FOR ENTRY</b>               |
|--------------------------|--|--------------------------------------|
| CF0                      | Set CW mode at F0                                | F0 parameter                         |
| CF1                      | Set CW mode at F1                                | F1 parameter                         |
| CF2                      | Set CW mode at F2                                | F2 parameter                         |
| CF3                      | Set CW mode at F3                                | F3 parameter                         |
| CF4                      | Set CW mode at F4                                | F4 parameter                         |
| CF5                      | Set CW mode at F5                                | F5 parameter                         |
| CF6                      | Set CW mode at F6                                | F6 parameter                         |
| CF7                      | Set CW mode at F7                                | F7 parameter                         |
| CF8                      | Set CW mode at F8                                | F8 parameter                         |
| CF9                      | Set CW mode at F9                                | F9 parameter                         |
| CM0                      | Set CW mode at M0                                | M0 parameter                         |
| CM1                      | Set CW mode at M1                                | M1 parameter                         |
| CM2                      | Set CW mode at M2                                | M2 parameter                         |
| CM3                      | Set CW mode at M3                                | M3 parameter                         |
| CM4                      | Set CW mode at M4                                | M4 parameter                         |
| CM5                      | Set CW mode at M5                                | M5 parameter                         |
| CM6                      | Set CW mode at M6                                | M6 parameter                         |
| CM7                      | Set CW mode at M7                                | M7 parameter                         |
| CM8                      | Set CW mode at M8                                | M8 parameter                         |
| CM9                      | Set CW mode at M9                                | M9 parameter                         |
| SQF                      | Scan to the next higher preset CW frequency.     | CW frequency parameter then selected |
| SQU                      | Scan up to the next higher preset CW frequency.  | CW frequency parameter then selected |
| SQD                      | Scan down to the next lower preset CW frequency. | CW frequency parameter then selected |
| ACW                      | Activates the currently scanned frequency as CW. | CW frequency parameter then selected |



**Programming Note:** CW generator response to a SQF command depends on the state the instrument is in at the time the command is received. For example, if the 680XXB is in a CW mode of operation with the current output frequency open for entry, the SQF command (1) causes the output to change to the next sequential frequency and (2) opens that frequency's parameter for data entry. However, if the instrument is in any other mode of operation, the SQF command causes it to switch to the last CW frequency that was output and opens that parameter for data entry.

Figure 2-2 is an example of a CW frequency command string.



**Figure 2-2.** Example of a CW Frequency Command String

**2-6 STEP SWEEP  
COMMANDS**

Table 2-6 (page 2-16) lists the step sweep command mnemonic codes. These commands are divided into five subclasses and are described in the following paragraphs.

**Step Sweep  
Range**

Seven step sweep ranges are available. The SF1 and SF3 commands select the sweep ranges of F1-F2 and F3-F4 respectively; the FUL command selects a full band sweep from the CW generator's low frequency limit to its high frequency limit.

The DF0, DF1, DF5, and DF6 commands each select a symmetrical frequency sweep around F0, F1, F5, and F6 respectively. The width of the sweep is determined by the  $\Delta F$  frequency parameter.

***Programming Examples:***

Programming "F1 2 GH F2 8 GH SF1" sets F1 to 2 GHz, F2 to 8 GHz, and implements a F1-F2 frequency sweep.

Programming "DLF 6 GH F5 7 GH DF5" sets  $\Delta F$  to 6 GHz, F5 to 7 GHz, and implements a F5- $\Delta F$  frequency sweep.

***Programming Note:***

If the commanded step sweep range is invalid, a parameter error (para. 2-20) will be generated, and the output of the CW generator will not be altered.

A step sweep range is invalid if the  $\Delta F$  frequency parameter results in a sweep that is outside the range of the instrument.

***Alternate  
Step Sweep***

Six alternate step sweep commands are available. If the 680XXB is sweeping when the alternate sweep command is received, the CW generator's output will alternate between the commanded sweep and the sweep then being executed.

***Programming Example:***

Assume that the 680XXB had been previously programmed and was then executing an F1-F2 sweep. Programming "AF3" would then activate the F3-F4 sweep and cause it to alternate with the F1-F2 sweep.

***Programming Note:***

An alternate step sweep command will only be recognized when the 680XXB has been programmed to sweep. It will be ignored at all other times.

***Sweep  
Triggering***

Two modes of sweep triggering are available over the bus—Automatic and Single. The AUT command selects automatic sweep triggering; the EXT command selects single sweep triggering.

When automatic sweep triggering is selected, the sweep continually sweeps from its start frequency (or power level) to its stop frequency (or power level) with optimal retrace time.

When single sweep triggering is selected, a single sweep starts when the TRG or TRS command is received. The RSS command resets the sweep to its start frequency (or power level), whenever the command is received while a single sweep is in progress.

**Table 2-6.** *Step Sweep Commands*

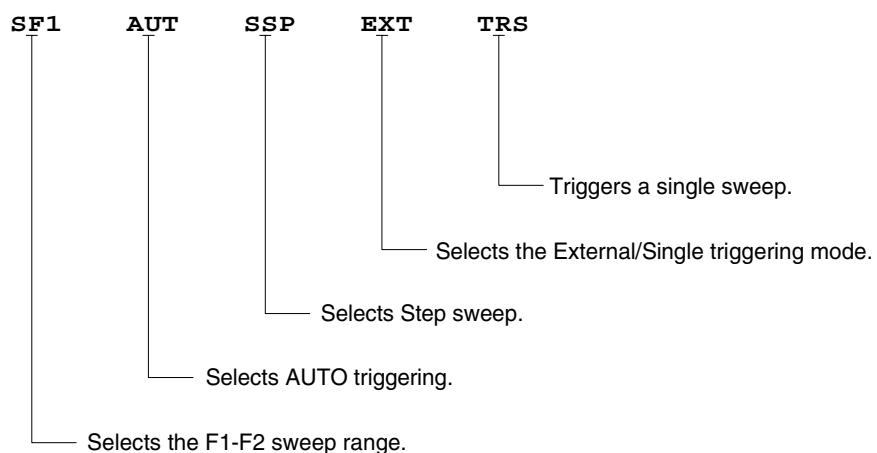
| MNEMONIC CODE  | FUNCTION                                    | OPENS FOR ENTRY |
|--|---|-----------------|
| <i>Step Sweep Range</i>                                  |   |                 |
| SF1  | Selects the F1-F2 step sweep mode           | None            |
| SF3  | Selects the F3-F4 step sweep mode           | None            |
| FUL  | Selects the Full Range step sweep mode      | None            |
| DF0  | Selects the F0- $\Delta$ F step sweep mode  | None            |
| DF1  | Selects the F1- $\Delta$ F step sweep mode  | None            |
| DF5  | Selects the F5- $\Delta$ F step sweep mode  | None            |
| DF6  | Selects the F6- $\Delta$ F step sweep mode  | None            |
| <i>Alternate Step Sweep</i>                              |   |                 |
| AFU  | Selects Full Range alternate step sweep     | None            |
| AF1  | Selects F1-F2 alternate step sweep          | None            |
| AF3  | Selects F3-F4 alternate step sweep          | None            |
| AD1  | Selects F1- $\Delta$ F alternate step sweep | None            |
| AD5  | Selects F5- $\Delta$ F alternate step sweep | None            |
| AD6  | Selects F6- $\Delta$ F alternate step sweep | None            |
| <i>Sweep Triggering</i>                                  |   |                 |
| AUT  | Selects Auto Trigger                        | None            |
| EXT  | Selects Single Trigger                      | None            |
| TRG  | Triggers a Single Sweep                     | None            |
| TRS  | Triggers a Single Sweep                     | None            |
| RSS  | Resets a Sweep if in progress               | None            |
| <i>Step Sweep Select</i>                                 |   |                 |
| SSP  | Selects Step Sweep                          | None            |
| MAN  | Selects Manual (Step) Sweep                 | None            |
| DU1  | Selects Dual Step Sweep mode                | None            |
| DU0  | Deselects Dual Step Sweep mode              | None            |
| TSS  | Steps to next point in DU1 mode             | None            |
| <i>Special Step Sweep<br/>(Steps Not Equally Spaced)</i> |   |                 |
| SP1  | Selects non-equally spaced step sweep       | None            |
| SP0  | Deselects non-equally spaced step sweep     | None            |

**Step Sweep  
Select**

Two commands are available—SSP selects a step sweep and MAN selects a manual (step) sweep. The selected step sweep mode applies to all sweep ranges. Figure 2-3 shows an example of a step sweep command string.

**Programming Note:**

The MAN command only provides for setting up the CW generator for a manual (step) sweep. It must be accompanied by the RL command to return the instrument to local (front panel) control in order for the operator to perform the manual (step) sweep.



---

**Figure 2-3.** Example of a Sweep Command String

***Dual Step Sweep Mode***

The dual step sweep mode provides for generating synchronized, step sweep outputs from two 680XXBs at a frequency offset. Figure 2-4 shows an example of dual step sweep programming.

---

```
10 !      "DUAL"
20 CLEAR
30 DISP "ENTER # OF STEPS"
40 INPUT S
50 DISP "ENTER WAIT TIME [mS]"
60 INPUT W
70 WAIT 100
80 DISP "ENTER 'LO' START FREQ [GHz]"
90 INPUT F1
100 DISP "ENTER 'LO' STOP FREQ [GHz]"
110 INPUT F2
120 DISP "ENTER OFFSET [GHz]"
130 INPUT F3
140 !
150 ! Initialize both 680XXB's
160 !
170 OUTPUT 705 ; "CF1F1";F1;"GHF2";F2;
    "GHSNS";S;"SPSSSPEXTCLO"
180 OUTPUT 706 ; "CF1F1";F1+F3;"GHF2";
    F2+F3;"GHSNS";S;"SPSSSPEXTCLO"
190 WAIT 1000
200 !
210 ! Set both to dual mode and enable
    GET to end DWELL
220 !
230 SEND 7 ; CMD "%&" DATA "GTLDU1SF1"
    EOL
240 WAIT 100
250 ! Trigger the sweep and wait for
    retrace to finish
260 SEND 7 ; CMD "%&" DATA "TRS" EOL
270 WAIT 100
280 ! Listen address both 681XXB's
290 SEND 7 ; CMD "%&"
300 FOR C+1 TO S+1
310 WAIT W
320 ! Trigger both to next point
330 TRIGGER 7
340 NEXT C
350 GOTO 260
```

---

**Figure 2-4.** Dual Step Sweep Programming Example

***Special Step  
Sweep***

This special step sweep provides for a step sweep that has non-equally spaced steps. It can be used in any of the available sweep ranges (F1-F2, F3-F4, Full, F0- $\Delta$ F, F1- $\Delta$ F, F5- $\Delta$ F, and F6- $\Delta$ F). The start frequency in this sweep must be equal to the first frequency programmed with the ZL(X000-999) command (para. 2-14). The intermediate steps can be programmed to be any frequency within the range of the programmed sweep.

***Programming Note:***

The SP1 command can be used with the dual step sweep mode.

Figure 2-5 shows an example of special step sweep programming.

---

For this example, assume a frequency sweep of 3 GHz to 10 GHz, with steps at 3, 6, 8, 9, and 10 GHz.

*Sample Coding in BASIC*

```
10 OUTPUT 705; "ZL000 3GH 6GH 8GH 9GH 10GH ZEL"  
20 OUTPUT 705; "F1 3GH F2 10GH SNS 4SPS"  
30 OUTPUT 705; "SP1 SSP SF1"
```

*Explanation of Code*

Line 10 sets up the step frequencies.

Line 20 sets start and stop frequencies and number of steps (frequency points - 1).

Line 30 set the CW generator to SP1, Step Sweep, and F1-F2 sweep range.

---

**Figure 2-5.** *Special Step Sweep Programming Example*

**2-7 FREQUENCY MARKER  
COMMANDS**

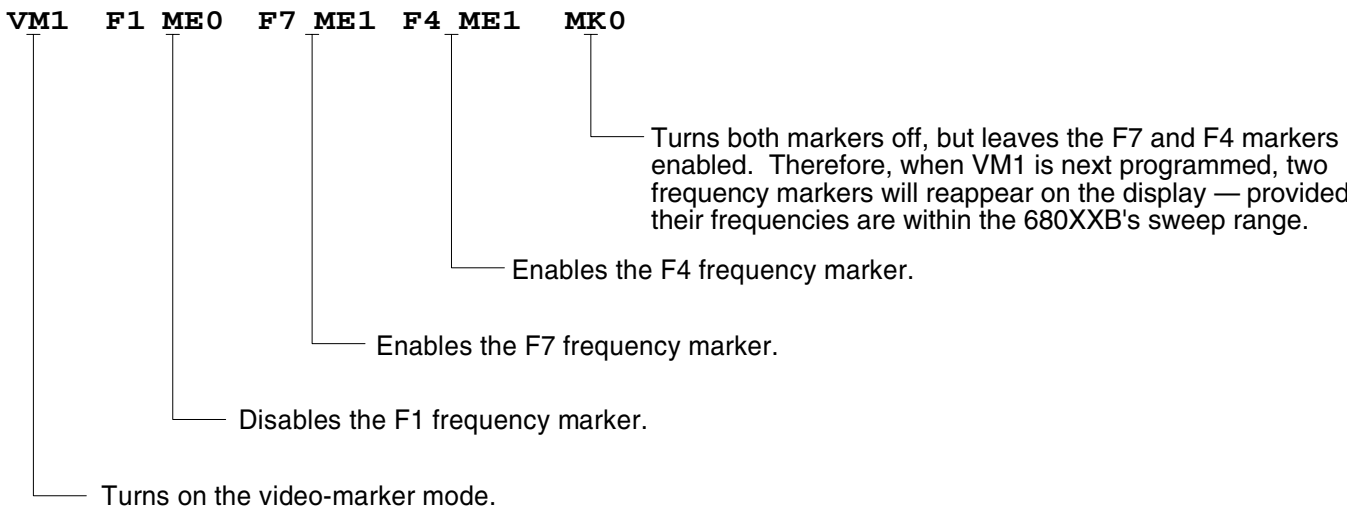
Table 2-7 lists the frequency marker command mnemonic codes. These commands provide for (1) selecting a CW frequency as a potential marker, (2) selecting a potential marker as an active marker, and (3) individually turning markers on and off.

The ME1 command will enable a marker at the current frequency that is open for update; the ME0 command will disable the same marker. If a frequency parameter is not open, no action will be taken. The VM1 command will turn on video markers. The MK0 command will turn all markers off.

Figure 2-6 shows an example of a frequency marker command string.

**Table 2-7.** *Frequency Marker Commands*

| MNEMONIC CODE | FUNCTION   | OPENS FOR ENTRY |
|---------------|--|-----------------|
| ME1           | Enables a marker at the active frequency (F0-F9 or M0-M9).             | None            |
| ME0           | Disables the marker at the active frequency.                           | None            |
| MK0           | Turns off markers. Enabled markers remain enabled, but are not active. | None            |
| VM1           | Turns on the video marker mode.  | None            |



**Figure 2-6.** *Example of a Frequency Marker Command String*

**2-8** **OUTPUT POWER  
LEVELING COMMANDS**

Table 2-8 lists the output power leveling command mnemonic codes. These commands provide for (1) selecting an RF output power level, (2) leveling the output power and (3) turning the output power leveling off. In addition, commands are provided for the level offset, ALC power slope, and step attenuator decoupling functions.

Figure 2-7 (page 2-24) shows an example of an output power level command string.

***RF Output  
Power Level  
Selection***

The commands, L0 thru L9, call up each of the preset (or previously set) output power levels. Each command causes its associated RF power level to be output and opens that power level's parameter for data entry. Each command will also deselect any other previously programmed power level and will turn off a power level sweep, if active.

***Alternate  
Sweep RF  
Output  
Power Level  
Selection***

In the alternate sweep mode, the commands, AL0 thru AL9, call up each of the preset (or previously set) L0 to L9 output power levels. Each command causes its associated RF power level to be output during the alternate sweep. Each command will also deselect any other previously programmed alternate sweep power level. The commands do **not** open the L1 to L9 power level parameters for data entry. Use the commands, XL0 thru XL9 or L0 thru L9, to enter new power level values.

***Output  
Power  
Leveling***

There are three output power leveling modes of operation—internal, external (detector or power meter), and fixed gain (leveling off). The IL1 command selects the internal leveling mode. In this mode, a signal from an internal level detector is used to level the output power. This is the default mode.

The DL1 command selects the external (detector) leveling mode; the PL1 command selects the external (power meter) leveling mode. In this mode, the output power is leveled using a signal from an external detector (power meter) connected to the EXTERNAL ALC IN connector. In the external power leveling mode, the EGI command provides for entering a setting for the Reference Level DAC to control the ALC gain. The LV0 command selects the fixed gain (leveling off) mode. Each command will also deselect any other previously programmed output power leveling mode.



***Programming Example:***

Programming “**PL1 EGI 140 SPS**” selects external leveling of the output power using a signal from an external power meter and sets the Reference Level DAC to 140.

**Table 2-8.** Power Leveling Commands (1 of 2)

| <b>MNEMONIC<br/>CODE</b> | <b>FUNCTION</b>   | <b>OPENS FOR<br/>ENTRY</b> |
|--------------------------|---|----------------------------|
| L0                       | Set RF output power level to L0   | L0                         |
| L1                       | Set RF output power level to L1   | L1                         |
| L2                       | Set RF output power level to L2   | L2                         |
| L3                       | Set RF output power level to L3   | L3                         |
| L4                       | Set RF output power level to L4   | L4                         |
| L5                       | Set RF output power level to L5   | L5                         |
| L6                       | Set RF output power level to L6   | L6                         |
| L7                       | Set RF output power level to L7   | L7                         |
| L8                       | Set RF output power level to L8   | L8                         |
| L9                       | Set RF output power level to L9   | L9                         |
| AL0                      | Set alternate sweep RF output level to L0   | None                       |
| AL1                      | Set alternate sweep RF output level to L1   | None                       |
| AL2                      | Set alternate sweep RF output level to L2   | None                       |
| AL3                      | Set alternate sweep RF output level to L3   | None                       |
| AL4                      | Set alternate sweep RF output level to L4   | None                       |
| AL5                      | Set alternate sweep RF output level to L5   | None                       |
| AL6                      | Set alternate sweep RF output level to L6   | None                       |
| AL7                      | Set alternate sweep RF output level to L7   | None                       |
| AL8                      | Set alternate sweep RF output level to L8   | None                       |
| AL9                      | Set alternate sweep RF output level to L9   | None                       |
| RF1                      | Turns on the RF output. (This is the default mode.)   | None                       |
| RF0                      | Turns off the RF output.  | None                       |
| LO1                      | Turns on the Level Offset function. The value of the Level Offset parameter is added to the level measured by the internal leveling loop. The resultant power level value is displayed. | None                       |
| LO0                      | Turns off the Level Offset function.  | None                       |
| IL1                      | Selects internal leveling of the output power. (This is the default mode.)<br>Deselects the DL1 or PL1 leveling modes, if previously programmed.  | None                       |

**Table 2-8.** *Power Leveling Commands (2 of 2)*

| <b>MNEMONIC<br/>CODE</b> | <b>FUNCTION</b>   | <b>OPENS FOR<br/>ENTRY</b> |
|--------------------------|---|----------------------------|
| DL1                      | Selects external leveling of the output power, using a signal from an external detector connected to the EXTERNAL ALC IN connector. Deselects the IL1 or PL1 leveling modes, if previously programmed.    | None                       |
| PL1                      | Selects external leveling of the output power using a signal from an external power meter connected to the EXTERNAL ALC IN connector. Deselects the IL1 and DL1 leveling modes, if previously programmed. | None                       |
| ELF                      | Selects front panel external leveling input.  | None                       |
| ELR                      | Selects rear panel external leveling input.   | None                       |
| LV0                      | Turns off leveling of the output power.   | None                       |
| LSP                      | Selects the Power Sweep mode. The power level will sweep as determined by the preset (or previously set) dwell-time and number-of-steps parameters.   | None                       |
| AT1                      | Selects ALC step attenuator decoupling.   | None                       |
| AT0                      | Deselects ALC step attenuator decoupling.   | None                       |
| ATT(xx)                  | Sets step attenuator value to xx ( $\times 10$ dB) in the ALC step attenuator decouple mode. xx is an unsigned integer between 00 (0 dB attenuation) and 11 (110 dB attenuation).                         | None                       |
| SL1                      | Turns on the ALC power slope function.  | None                       |
| SL0                      | Turns off the ALC power slope function.   | None                       |
| EGO                      | Outputs the value of the Reference Level DAC setting in external power leveling mode.   | None                       |

***ALC Power  
Slope***

The ALC power slope function provides for linearly increasing or decreasing output power as the frequency increases to compensate for system, cable, and waveguide variations due to changes in frequency. The SL1 command turns on the ALC power slope function. The power slope value is changed using the SLP command and the pivot point frequency is changed using the PVT command. The SL0 command turns off the ALC power slope function.

***Programming Example:***

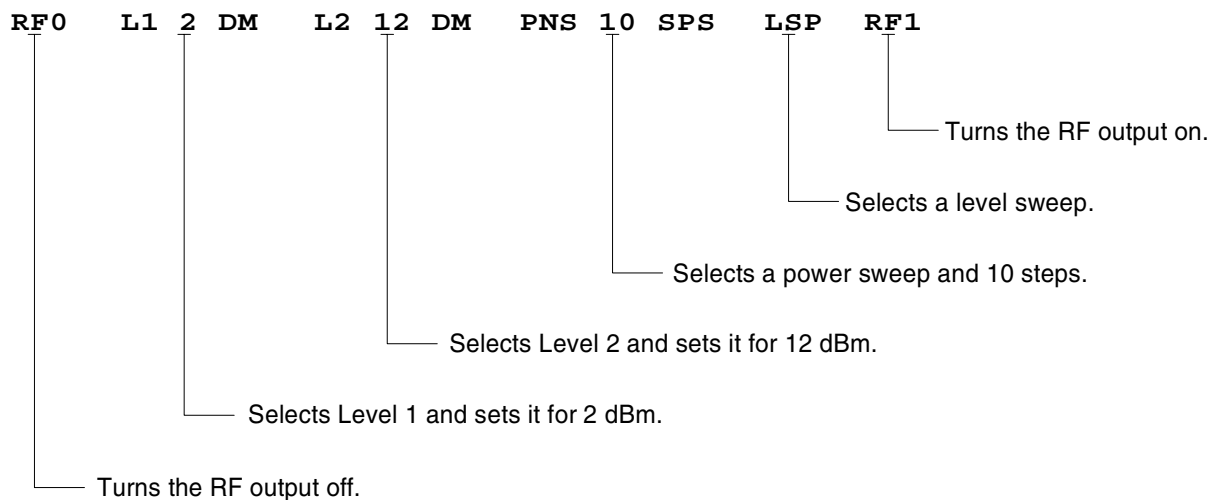
Programming “**SL1 SLP 128 SPS PVT 2.0 GH**” turns on the ALC power slope function and sets the power slope value to 128 and the pivot point frequency to 2 GHz.

***Attenuator  
Decoupling***

The attenuator decoupling function provides for decoupling of the step attenuator (if equipped) from the ALC system. The AT1 command decouples the step attenuator, the ATT(xx) command provides for setting the step attenuator value for 0 to 110 dB in 10 dB increments, and the AT0 command deselects the attenuator decoupling function.

***Programming Example:***

Programming “**AT1 ATT08**” decouples the step attenuator from the ALC system and sets the step attenuator value to 80 dB.



**Figure 2-7.** Example of an Output Power Level Command String

**2-9 OUTPUT COMMANDS**

Table 2-9 lists the output command mnemonic codes. These commands provide for the output of data from the CW generator to the controller. Figure 2-8 (page 2-27) shows examples of output command programming.

**Table 2-9.** *Output Commands (1 of 3)*

| MNEMONIC<br>CODE | FUNCTION   |
|------------------|--|
| *IDN?            | Causes the CW generator to return an identification string in IEEE-488.2 specified <NR1> format (four fields separated by commas). The fields are:<Manufacturer>, <Model>, <Serial #>, <Firmware revision level>; where the actual model number, serial number, and firmware version of the 680XXB will be passed.   |
| OI               | Causes the CW generator to identify itself by sending the following parameter information over the bus; model number, low-end frequency, high-end frequency, minimum output power level, maximum output power level, software revision number, serial number, model prefix (A or B), and series (1 or 2). This command can be used to send parameter information to the controller automatically, thus relieving the operator from having to input the information manually. The string is 36 characters long. |
| OFL              | Returns the low-end frequency value (in MHz) to the controller.  |
| OFH              | Returns the high-end frequency value (in MHz) to the controller.   |
| OF0              | Returns the F0 frequency value (in MHz) to the controller.   |
| OF1              | Returns the F1 frequency value (in MHz) to the controller.   |
| OF2              | Returns the F2 frequency value (in MHz) to the controller.   |
| OF3              | Returns the F3 frequency value (in MHz) to the controller.   |
| OF4              | Returns the F4 frequency value (in MHz) to the controller.   |
| OF5              | Returns the F5 frequency value (in MHz) to the controller.   |
| OF6              | Returns the F6 frequency value (in MHz) to the controller.   |
| OF7              | Returns the F7 frequency value (in MHz) to the controller.   |
| OF8              | Returns the F8 frequency value (in MHz) to the controller.   |
| OF9              | Returns the F9 frequency value (in MHz) to the controller.   |
| OM0              | Returns the M0 frequency value (in MHz) to the controller.   |

**Table 2-9.** *Output Commands (2 of 3)*

| <b>MNEMONIC<br/>CODE</b> | <b>FUNCTION</b>  |
|--------------------------|--|
| OM1                      | Returns the M1 frequency value (in MHz) to the controller.           |
| OM2                      | Returns the M2 frequency value (in MHz) to the controller.           |
| OM3                      | Returns the M3 frequency value (in MHz) to the controller.           |
| OM4                      | Returns the M4 frequency value (in MHz) to the controller.           |
| OM5                      | Returns the M5 frequency value (in MHz) to the controller.           |
| OM6                      | Returns the M6 frequency value (in MHz) to the controller.           |
| OM7                      | Returns the M7 frequency value (in MHz) to the controller.           |
| OM8                      | Returns the M8 frequency value (in MHz) to the controller.           |
| OM9                      | Returns the M9 frequency value (in MHz) to the controller.           |
| OL0                      | Returns the L0 power value (in dBm) to the controller.               |
| OL1                      | Returns the L1 power value (in dBm) to the controller.               |
| OL2                      | Returns the L2 power value (in dBm) to the controller.               |
| OL3                      | Returns the L3 power value (in dBm) to the controller.               |
| OL4                      | Returns the L4 power value (in dBm) to the controller.               |
| OL5                      | Returns the L5 power value (in dBm) to the controller.               |
| OL6                      | Returns the L6 power value (in dBm) to the controller.               |
| OL7                      | Returns the L7 power value (in dBm) to the controller.               |
| OL8                      | Returns the L8 power value (in dBm) to the controller.               |
| OL9                      | Returns the L9 power value (in dBm) to the controller.               |
| OLO                      | Returns the Level Offset power value (in dB) to the controller.      |
| ODF                      | Returns the $\Delta F$ frequency value (in MHz) to the controller.   |
| OPD                      | Returns the dwell time of the power sweep (in ms) to the controller. |
| OPS                      | Returns the number-of-steps of the power sweep to the controller.    |
| OSD                      | Returns the dwell time of the step sweep (in ms) to the controller.  |

**Table 2-9.** *Output Commands (3 of 3)*

| MNEMONIC<br>CODE | FUNCTION  |
|------------------|---|
| OSS              | Returns the number-of-steps of the step sweep to the controller.        |
| OST              | Returns the sweep time value (in ms) to the controller.                 |
| OVN              | Returns the ROM version number to the controller.                       |
| OWT              | Returns the GPIB termination status to the controller. (0=CR; 1=CRLF)   |
| OSE              | Returns the last GPIB syntax error to the controller.                   |
| OEM              | Returns the Extended SRQ Mask bytes (3 binary bytes) to the controller. |
| OES              | Returns the GPIB Status bytes (3 binary bytes) to the controller.       |
| OSB              | Returns the Primary GPIB Status byte to the controller.                 |
| OSM              | Returns the Primary SRQ Mask byte to the controller.                    |
| OSR              | Returns the self-test results (6 binary bytes) to the controller.       |

```
760 OUTPUT 705;"OF1"
770 ENTER 705;A
780 PRINT "F1 is set at ";A;" MHz"
```

```
1050 OUTPUT 705;"OSS"
1060 ENTER 705;A
1070 PRINT "Step Sweep has ";A;" Steps"
```

**Figure 2-8.** *Output Command Programming Examples*

**2-10 STORED SETUP  
COMMANDS**

Table 2-10 (page 2-28) lists the stored setup command mnemonic codes. These commands provide for saving instrument setups and recalling them for use.

A current instrument setup can be saved to internal setup memory using the SSN(M<sub>1</sub> to 9) command, where M = memory locations 1 to 9. Up to nine instrument setups can be stored in this manner. The command RSN(M<sub>1</sub> to 9) recalls a stored instrument setup from internal setup memory locations 1 to 9.

If more than nine instrument setups are needed, or if it is desirable to store the setups in the controller instead of the CW generator memory,

the 680XXB can be commanded to output and accept stored setups over the bus.

The SAF command outputs the current instrument setup to the controller in a 300-byte (approximately) binary data string. The controller stores the instrument setup. The RCF command readies the CW generator to receive a new instrument setup recalled from the controller. Figure 2-9 shows an example of SAF and RCF command programming.

The SAM and RCM commands perform the same functions as described for the SAF and RCF commands, except that all of the stored instrument setups are included in the binary data string along with the current instrument setup. For these commands, the binary data string is approximately 3000 bytes long.

**Table 2-10.** *Stored Setup Commands*

| MNEMONIC CODE          | FUNCTION   |
|------------------------|--|
| SAF                    | Outputs the current instrument setup to the controller.  |
| SAM                    | Outputs both the current instrument setup and all stored instrument setups to the controller.            |
| SM                     | Recalls the next stored instrument setup in sequence.  |
| SSN(M <sub>1-9</sub> ) | Saves the current instrument setup to internal setup memory location M, where M = 1 to 9.                |
| RCF                    | Readies the 680XXB to receive a new instrument setup recalled from the controller.                       |
| RCM                    | Readies the 680XXB to receive a new instrument setup and new stored setups recalled from the controller. |
| RSN(M <sub>1-9</sub> ) | Recalls the instrument setup stored in internal setup memory location M, where M = 1 to 9.               |

**Programming Note:** The SAF and SAM commands output binary data. The data string is terminated with “EOI” on the last byte sent (no CR or LF is sent).

```

10 DIM A$ [300]
20 OUTPUT 705; "SAF"
30 ENTER 705 USING "%, %K"; A$ (Requires EOI
   to be the terminator of the read.)
40 OUTPUT 705; "RCF"; A$ (A$ must follow the SAF.)

```

**Figure 2-9.** *SAF and RCF Commands Programming Example*

**2-11 SRQ AND STATUS  
BYTE COMMANDS**

Table 2-11 (page 2-31) lists the Service Request (SRQ) and Status Byte command mnemonic codes. These commands enable the CW generator to request service from the controller when certain, predefined conditions exist.

**Status Bytes** The 680XXB has three GPIB status bytes—the primary and two extended status bytes. Figure 2-10 shows the three status bytes and identifies the status reporting function of each status byte bit.

Each status reporting bit, with the exception of primary status byte bit 6 (SRQ), is set when the condition on which it reports is detected. These changes in status byte bit settings can be read by the controller as follows:

- The contents of the primary status byte is returned to the controller in response to a serial poll or the OSB command.
- The contents of the primary status byte and the two extended status bytes are returned to the controller in response to the OES command. Figure 2-11 (page 2-32) shows an example of OES command programming.

**SRQ  
Generation**

The CW generator can generate GPIB service requests (SRQs) to report instrument status and syntax errors to the controller. The CW generator will generate an SRQ if:

1. The SRQ generation function has been enabled using the SQ1 command *and*,
2. One (or more) of the status reporting functions is true *and*,
3. The primary status byte bit associated with the true status reporting function has been enabled.

Bits in the primary status byte can be enabled by either of two methods. The first uses the FB1/FB0, ES1/ES0, UL1/UL0, LE1/LE0, PE1/PE0, SE1/SE0, and SB1/SB0 commands, described in Table 2-11, to individually enable or disable each bit. The second method uses a single 8-bit status byte mask (MB0) to enable any or all of the primary status byte bits.

Figure 2-12 (page 2-33) shows examples of status byte mask programming.



**NOTE**

All status byte bits are latched except for those indicated with the “\*”. Once set, an OES or OSB command must be received before the condition will be reset. The primary status byte bit 6 (SRQ) is cleared by a serial poll only.

**Primary Status Byte**

|                        |                      |                      |                       |                     |                     |                     |                        |
|------------------------|----------------------|----------------------|-----------------------|---------------------|---------------------|---------------------|------------------------|
| Extended Status Byte 2 | SRQ                  | Syntax Error         | Parameter Range Error | Lock Error          | RF Unleveled        | End of Sweep        | Extended Status Byte 1 |
| <i>Bit 7</i><br>(128)  | <i>Bit 6</i><br>(64) | <i>Bit 5</i><br>(32) | <i>Bit 4</i><br>(16)  | <i>Bit 3</i><br>(8) | <i>Bit 2</i><br>(4) | <i>Bit 1</i><br>(2) | <i>Bit 0</i><br>(1)    |

Primary status byte bit 0 is set whenever one of the status conditions reported by an extended status byte 1 is true and the associated status bit is enabled. This bit is cleared when the controller sends the OES command.

Primary status byte bit 7 is set whenever one of the status conditions reported by an extended status byte 2 is true and the associated status bit is enabled. This bit is cleared when the controller sends the OES command.

Primary status byte bit 6 (SRQ) is not maskable. This bit is set by the SQ1 command and cleared by a serial poll.

**Extended Status Byte 1**

|                       |                      |                      |                      |                     |                     |                     |                     |
|-----------------------|----------------------|----------------------|----------------------|---------------------|---------------------|---------------------|---------------------|
| Not Used              | Not Used             | Not Used             | Not Used             | RF* Locked          | Self Test Completed | Not Used            | Self Test Failed    |
| <i>Bit 7</i><br>(128) | <i>Bit 6</i><br>(64) | <i>Bit 5</i><br>(32) | <i>Bit 4</i><br>(16) | <i>Bit 3</i><br>(8) | <i>Bit 2</i><br>(4) | <i>Bit 1</i><br>(2) | <i>Bit 0</i><br>(1) |

Extended status byte 1 bits are enabled by the extended status byte 1 mask command, MB1.

Extended status byte 1 bit 0 (SelfTest Failed) and bit 2 (Self Test Complete) should not be unmasked at the same time.

Extended status byte 1 bit 3 (RF Locked) is only used with the Model 360B interface. The setting of this bit is blocked or unblocked by the commands, LS0 and LS1 (See Table 2-11).

**Extended Status Byte 2**

|                       |                             |                      |                      |                      |                           |                     |                     |
|-----------------------|-----------------------------|----------------------|----------------------|----------------------|---------------------------|---------------------|---------------------|
| Parameter* Changed    | Calibrate Function Finished | Not Used             | RF* Unlocked         | Crystal Oven Failure | Calibrate Function Failed | Not Used            | Not Used            |
| <i>Bit 7</i><br>(128) | <i>Bit 6</i><br>(64)        | <i>Bit 5</i><br>(32) | <i>Bit 4</i><br>(16) | <i>Bit 3</i><br>(8)  | <i>Bit 2</i><br>(4)       | <i>Bit 1</i><br>(2) | <i>Bit 0</i><br>(1) |

Extended status byte 2 bits are enabled by the extended status byte 2 mask command, MB2.

The setting of extended status byte 2 bit 4 (RF Unlocked) is blocked or unblocked by the commands, EL0 and EL1 (See Table 2-11).

Extended status byte 2 bit 7 (Parameter Changed) is only used with the Model 562 interface. The setting of this bit is blocked or unblocked by the commands, I10 and I11 (See Table 2-11).

**Figure 2-10.** Primary and Extended Status Bytes

**Table 2-11.** *SRQ and Status Byte Commands (1 of 2)*

| <b>MNEMONIC<br/>CODE</b> | <b>FUNCTION</b>  |
|--------------------------|--|
| ES1                      | Enables an SRQ to be generated when Primary Status Byte bit 1 (End of Sweep) is set and SQ1 has been programmed.   |
| ES0                      | Inhibits an SRQ from being generated when the End of Sweep bit is set. This is the default mode.   |
| FB1                      | Enables an SRQ to be generated when Primary Status Byte bit 0 (Extended Status Byte 1) is set and SQ1 has been programmed. The Extended Status Byte 1 bit is set whenever one (or more) of the unmasked status reporting functions in Extended Status Byte 1 is true.  |
| FB0                      | Inhibits an SRQ from being generated when the Extended Status Byte 1 bit is set. This is the default mode.   |
| LE1                      | Enables an SRQ to be generated when Primary Status Byte bit 3 (Lock Error) is set and SQ1 has been programmed.   |
| LE0                      | Inhibits an SRQ from being generated when the Lock Error bit is set. This is the default mode.   |
| MB0                      | Sets an 8-bit data mask that is used to enable specific bits of the Primary Status Byte (Figure 2-12). This enables any or all of the bits (except for bit 6) in the Primary Status Byte to generate an SRQ using one 8-bit byte. This command can be equivalent to sending ES1, FB1, LE1, PE1, SE1, SB1, and UL1. |
| MB1                      | Sets the enable mask byte for Extended Status Byte 1.  |
| MB2                      | Sets the enable mask byte for Extended Status Byte 2.  |
| PE1                      | Enables an SRQ to be generated when Primary Status Byte bit 4 (Parameter Range Error) is set and SQ1 has been programmed.  |
| PE0                      | Inhibits an SRQ from being generated when the Parameter Range Error bit is set. This is the default mode.  |
| SB1                      | Enables an SRQ to be generated when Primary Status Byte bit 7 (Extended Status Byte 2) is set and SQ1 has been programmed. The Extended Status Byte 2 bit is set whenever one (or more) of the unmasked status reporting functions in Extended Status Byte 2 is true.  |
| SB0                      | Inhibits an SRQ from being generated when the Extended Status Byte 2 bit is set. This is the default mode.   |
| SE1                      | Enables an SRQ to be generated when Primary Status Byte bit 5 (Syntax Error) is set and SQ1 has been programmed.   |

**Table 2-11.** *SRQ and Status Byte Commands (2 of 2)*

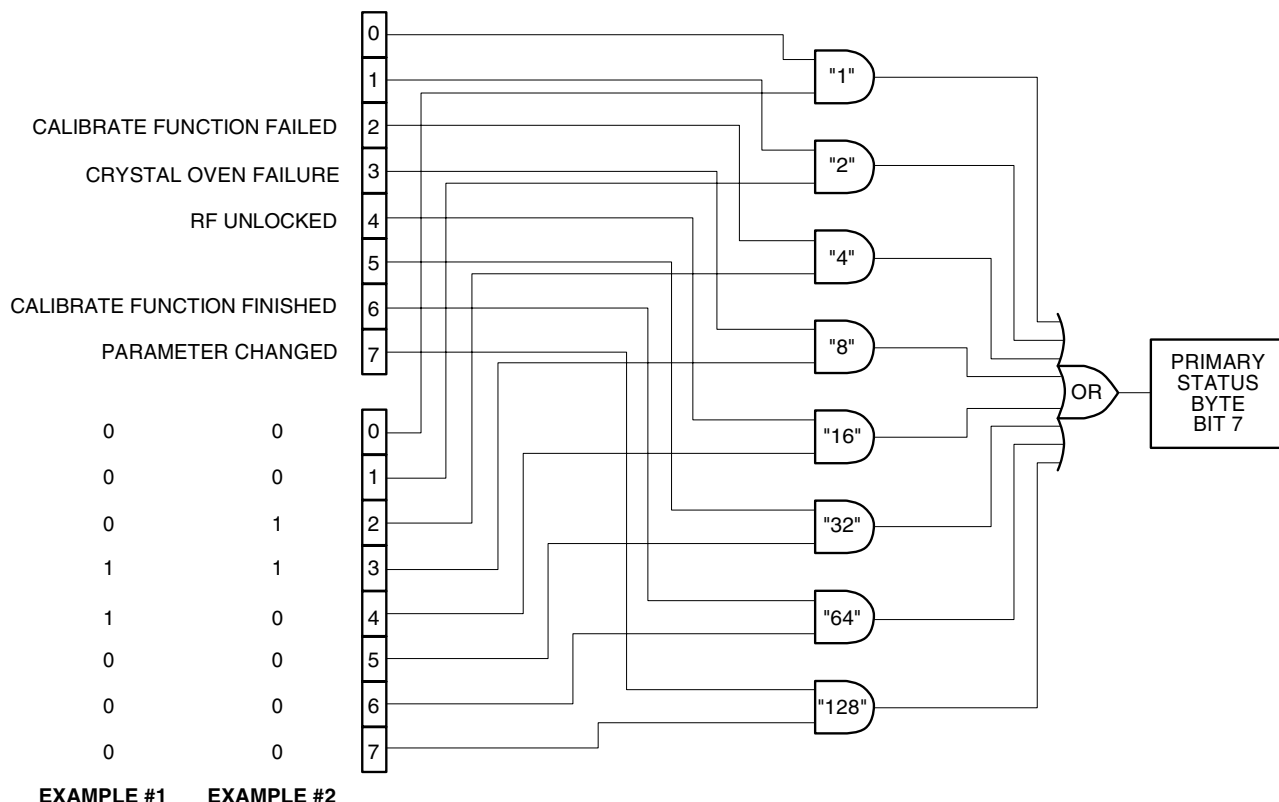
| <b>MNEMONIC<br/>CODE</b> | <b>FUNCTION</b>  |
|--------------------------|--|
| SE0                      | Inhibits an SRQ from being generated when the Syntax Error bit is set. This is the default mode.   |
| SQ1                      | Enables the SRQ generation function. This command allows a status reporting function, that is true and enabled, to pull the SRQ line LOW (true) and request service from the controller.                               |
| SQ0                      | Disables the SRQ generation function. This is the default mode.  |
| UL1                      | Enables an SRQ to be generated when Primary Status Byte bit 2 (RF Unleveled) is set and SQ1 has been programmed.   |
| UL0                      | Inhibits an SRQ from being generated when the RF Unleveled bit is set. This is the default mode.   |
| LS1                      | Unblocks updating of the Extended Status Byte 1 bit 3 (RF Locked). This bit is only used with the Model 360B interface.  |
| LS0                      | Disables updating of the Extended Status Byte 1 bit 3. This is the default setting.  |
| EL1                      | Unblocks updating of the Extended Status Byte 2 bit 4 (RF Unlocked).   |
| ELO                      | Blocks updating of the Extended Status Byte 2 bit 4. This is the default setting because it is normal for the RF to be momentarily unlocked during sweeps and sweep retrace.   |
| II1                      | Unblocks updating of the Extended Status Byte 2 bit 7 (Parameter Changed). This bit is only used with the Model 562 interface. This bit is cleared when the 562 sends the OCP command (Output Last Parameter Changed). |
| II0                      | Disables updating of the Extended Status Byte 2 bit 7. This is the default setting.  |
| CSB                      | Clears all GPIB status bytes.  |

```
OUTPUT 705; "OES"  
ENTER 705 USING "#, B"; A, B, C  
MAIN = A  
1 EXT = B  
2 EXT = C
```

**Figure 2-11.** *OES Command Programming Example*

The 680XXB has a software mask that permits manipulation of the three status bytes over the bus. This manipulation is accomplished by sending the command codes MB0, MB1, MB2, or all three at once, followed by an argument that assigns an on/off condition for each bit in the byte. Two examples are shown below:

**EXTENDED STATUS BYTE 2**



**MASK BYTE 2**

EXAMPLE #1: **"MB2" (CHR \$(24))**

Sets bits 3 and 4 in Mask Byte 2 to 1 and all other bits to 0, thus enabling bits 3 and 4 in Extended Status Byte 2 to be read from the bit 7 position of the Primary Status Byte.

EXAMPLE #2: **"MB2" (CHR \$(12))**

Sets bits 2 and 3 in Mask Byte 1 to 1 and all other bits to 0, thus enabling bits 2 and 3 in Extended Status Byte 2 to be read from the bit 7 position of the Primary Status Byte.

**Figure 2-12.** Status Byte Mask Programming Examples

**2-12 CONFIGURATION  
COMMANDS**

Table 2-12 lists the configuration command mnemonic codes. These commands permit selection/setting of the following system configuration items via the bus:

- ❑ A +5V or –5V level for the rear panel retrace and bandswitch blanking outputs.
- ❑ Setting the frequency scaling reference multiplier value.
- ❑ Normally-open or normally-closed contacts on the internal penlift relay.
- ❑ RF on or RF off during frequency switching in CW and step sweep modes.
- ❑ RF on or RF off during sweep retrace.
- ❑ RF on or RF off at reset.
- ❑ 0V or 10V ramp rest point.
- ❑ 40 dB or 0 dB of attenuation when RF is switched off in units with a step attenuator (Option 2).

The system configuration selections made with GPIB commands remain in effect when the instrument is returned to local control.

**Table 2-12.** Configuration Commands (1 of 2)

| MNEMONIC<br>CODE | FUNCTION   |
|------------------|--|
| BPN              | Selects a –5V level for the retrace and bandswitch blanking outputs. (The retrace blanking output signal is available at pin 6 of the AUX I/O connector; the bandswitch blanking output signal at pin 20 of the AUX I/O connector.)  |
| BPP              | Selects a +5V level for the retrace and bandswitch blanking outputs.   |
| FRS              | Permits setting the frequency scaling reference multiplier value. The multiplier value must be between 0.1 and 14 and must be terminated with TMS.<br><b>Programming Example:</b><br>Programming “ <b>FRS 3 TMS</b> ” sets the frequency scaling reference multiplier to 3.<br>This command affects all entered and displayed frequencies, but does not affect the output of the instrument. |
| PPO              | Selects normally-open contacts on the internal penlift relay. (The penlift relay output, optionally available at the rear panel, is used to lift a plotter pen during retrace.)  |
| PPC              | Selects normally-closed contacts on the internal penlift relay.  |
| RC0              | Selects RF to be off during frequency switching in CW and step sweep modes.  |

**Table 2-12.** *Configuration Commands (2 of 2)*

| <b>MNEMONIC<br/>CODE</b> | <b>FUNCTION</b>   |
|--------------------------|---|
| RC1                      | Selects RF to be on during frequency switching in CW and step sweep modes.  |
| RT0                      | Selects RF to be off during retrace.  |
| RT1                      | Selects RF to be on during retrace.   |
| RO0                      | Selects RF to be on at reset. (This is the default mode.)   |
| RO1                      | Selects RF to be off at reset.  |
| RR0                      | Selects 0V for the ramp rest point for sweeps triggered by a single trigger or external trigger. (The ramp is available at the rear panel HORIZ OUT connector and pin 1 of the AUX I/O connector.)                                |
| RR1                      | Selects 10V for the ramp rest point.  |
| TR0                      | Sets 0 dB of attenuation when RF is switched off in units with a step attenuator (Option 2) installed. If Option 2 is not installed, this command produces a syntax error.  |
| TR1                      | Sets 40 dB (minimum) of attenuation when RF is switched off in units with a step attenuator (Option 2) installed. This provides a better output source match. If Option 2 is not installed, this command produces a syntax error. |

**2-13** **GROUP EXECUTE  
TRIGGER COMMANDS**

Table 2-13 lists the group execute trigger (GET) command mnemonic codes. These commands let a GET bus message (Table 1-3) be used to trigger certain CW generator functions and thus speed up bus operations.

In the default state, the 680XXB responds to a GET message by triggering a single sweep.

**Table 2-13.** *Group Execute Trigger Commands*

| <b>MNEMONIC<br/>CODE</b> | <b>FUNCTION</b>   |
|--------------------------|---|
| GTC                      | Configures the 680XXB to execute an SQF command (scan to the next higher preset CW frequency) each time a GET message is received.      |
| GTD                      | Configures the 680XXB to execute a DN command (steps the open parameter down by the step size) each time a GET message is received.     |
| GTF                      | Configures the 680XXB to execute a fast-frequency-switching step (Table 2-14) each time a GET message is received.                      |
| GTL                      | Configures the 680XXB to execute a TSS command (steps to the next point in a dual step sweep mode) each time a GET message is received. |
| GTO                      | Disables the GET functions.   |
| GTS                      | Configures the 680XXB to execute a TRS command (trigger a single sweep) each time a GET message is received. This is the default mode.  |
| GTT                      | Configures the 680XXB to execute a TST command (execute a complete CW generator self test) each time a GET message is received.         |
| GTU                      | Configures the 680XXB to execute a UP command (steps the open parameter up by the step size) each time a GET message is received.       |
| Y                        | Sending a "Y" is equivalent to sending a GET.   |

**2-14 FAST-FREQUENCY-  
SWITCHING  
COMMANDS**

Table 2-14 lists the fast-frequency-switching command mnemonic codes. These commands provide for reducing the time that it takes to switch between two CW frequencies.

In the fast-frequency-switching mode, up to 1000 frequencies can be loaded into a stack. A stack pointer can then be set to point to a specific frequency on the stack and the CW generator commanded to switch from that frequency through the following stack frequencies to the bottom of the stack. Figure 2-13 provides an example of fast-frequency-switching programming.

**Table 2-14.** *Fast-Frequency-Switching Commands*

| MNEMONIC<br>CODE | FUNCTION   |
|------------------|--|
| ZL(X000-999)     | Loads a CW frequency into the stack at location X. The location is a number from 000 to 999. |
| ZEL              | Ends frequency loading.  |
| ZS(X000-999)     | Sets the stack pointer to point to location X. The location is a number from 000 to 999.     |

```

OUTPUT 705; "ZL000" . . . Set pointer for load
OUTPUT 705; "10 GH, 11 GH, 12 GH, 13 GH"
OUTPUT 705; "ZEL GTF"
NEW
OUTPUT 705; "ZS000" . . . Set pointer to start
TRIGGER 705; . . . . Sets 10 GHz
TRIGGER 705; . . . . Sets 11 GHz
TRIGGER 705; . . . . Sets 12 GHz
TRIGGER 705; . . . . Sets 13 GHz
GO TO NEW
    
```

**Figure 2-13.** *Fast-Frequency-Switching Programming Example*



**2-15 POWER-OFFSET-  
TABLE COMMANDS**

Table 2-15 lists the power-offset-table command mnemonic codes. These commands provide for maintaining a consistent power level at a point within a test setup across the measurement frequencies. This “flattening” of the test point power level is accomplished by summing a power offset word (from the power offset table) with the CW generator's normal power level DAC word at each frequency point.

The power-offset mode works in conjunction with the fast-frequency-switching mode (para. 2-14). The frequency stack must be loaded before loading the power-offset table because the frequency loading sets the upper limit for the number of entries in the power-offset table. The same pointer is used for both the frequency stack and the power-offset table. Once the power-offset table is loaded, the PT1 command turns on the power-offset mode; the PT0 command turns it off.

**Loading the  
Power-Offset  
Table**

To load the power-offset table, use the command, PTL clch dldh....., where “clch” is the number of power-offset words and “dldh” is a power-offset word. Both “clch” and “dldh” are two-byte binary words sent LOW byte first and HIGH byte second. The power-offset word is in hundredths of a dB. Negative power offsets use 2's complement representation.

To change a power-offset word in the table, use the PTC dldh command, where “dldh” is the new power-offset word for the current power level setting.

**Programming Note:**

Care must be taken to send the exact number of power-offset words specified in the wordcount, “clch”. If too few words are sent, the GPIB interface may not respond properly.

Figures 2-14 and 2-14a show an example of power-offset mode programming.

**Table 2-15.** Power-Offset-Table Commands

| MNEMONIC<br>CODE | FUNCTION   |
|------------------|--|
| PT0              | Disable the Power Offset Table   |
| PT1              | Enable the Power Offset Table  |
| PTC              | Change a Power Offset Table entry (PTC dldh), where dldh is the new offset word for the current table entry. |
| PTL              | Load a Power Offset Table (PTL clch dldh ...), where clch is the data word count and dldh is the data word.  |

The following is an example of power-offset mode programming. This program is written for use with an IBM-PC type computer/controller containing an IOtech GPIB interface.

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>

/* IOtech Driver488/LIB Subroutine Interface definitions... */
#include "\ieee488\iotlib.h"
#include "\ieee488\iot_main.h"

/* Define the device handles */
DevHandleT Synth, ieee;

void main()
{
    char CmdString[10], DataString[40], String[40];
    unsigned char XString[160];

    int next_step, i, j;

    /******
    /* Initialize the IOtech interface board and */
    /* obtain the interface's handle.          */
    /******

#define ADDRESS 5

if((ieee=InitIeee488(btMP488CT, 21, -1, 0x02e1, 7, 5, 1, 10000,0))== -1)
{
    printf("Cannot initialize IEEE 488 system.\n");
    exit(1);
}

if(( Synth=CreateDevice( ADDRESS, -1 ) )== -1)
{
    printf("Cannot create Synth device.\n");
    exit(1);
}

/* Set the device timeout so you don't wait forever if there's a problem */
TimeOut(Synth, 2000);

/* Handle the errors in the program */
Error(Synth, OFF);

/******

/* Address the Synthesizer to listen */
```

NOTE: This program is continued in Figure 2-14a.

---

**Figure 2-14.** Power-Offset Mode Programming Example (1 of 2)

```
strcpy(XString, "_?U%");
SendCmd(Synth, XString, strlen(XString));

Output(Synth, "RST");
Output(Synth, "GTF");
Output(Synth, "ZL000");
Output(Synth, "1 GH 2 GH 3 GH 4 GH 5 GH 6 GH 7 GH 8 GH 9 GH 10 GH");
Output(Synth, "ZEL");

/* Make a data array with the PTL command, the word count */
/* and the binary data in low-byte, high-byte order.      */
DataString[0]='P';
DataString[1]='T';
DataString[2]='L';
DataString[3]=10;      /* Low byte  --  ten words */
DataString[4]=0;      /* High byte --          */
DataString[5]=0;      /* 0 */
DataString[6]=0;
DataString[7]=20;     /* 276 */
DataString[8]=1;
DataString[9]=30;     /* 542 */
DataString[10]=2;
DataString[11]=40;    /* 808 */
DataString[12]=3;
DataString[13]=50;    /* 1074 */
DataString[14]=4;
DataString[15]=60;    /* 1340 */
DataString[16]=5;
DataString[17]=70;    /* 1606 */
DataString[18]=6;
DataString[19]=80;    /* 1872 */
DataString[20]=7;
DataString[21]=90;    /* 2138 */
DataString[22]=8;
DataString[23]=100;   /* 2404 */
DataString[24]=9;

/* Send the data with an EOI on the last byte */
SendEoi(Synth, DataString, 25);

Output(Synth, "PT1");
Output(Synth, "ZS000");

for(next_step=0;next_step<10;next_step++)
{
    Output(Synth, "Y");
    printf("Press Enter for Next Frequency");
    getchar();
}

} /* End of main() */
```

---

**Figure 2-14a.** Power-Offset Mode Programming Example (2 of 2)

**2-16 USER LEVEL  
CALIBRATION  
COMMANDS**

Table 2-16 lists the user level calibration commands. These commands provide for (1) activating individual user level calibration tables, (2) sending the tables to the controller, and (3) recalling the tables from the controller.

The user level (flatness correction) calibration function provides for calibrating out path variations in a test setup. This is accomplished by means of an entered power-offset table from a GPIB power meter or calculated data. When the user level calibration table is activated, the set power level is delivered to the point in the test setup where the calibration was performed. Up to five user level calibration tables from 2 to 801 frequency points/table can be created and stored in 680XXB memory for recall. (Refer to the 680XXB Operation Manual, page 3-52, for user level calibration procedures.)

The commands, LU1 thru LU5, each activate an individual user level calibration table (#1 thru #5). The LU0 command turns off the active user level calibration table. The LUS command sends all five tables of user level calibration data to the controller where they are stored in a binary data file. While stored in the file, the data can be edited (see page 2-44). The LUR command readies the 680XXB to receive the five tables of user level calibration data from the controller. Figures 2-15 thru 2-15b show an example program for saving and recalling user level calibration tables.

**Table 2-16.** *User Level Calibration Commands*

| <b>MNEMONIC<br/>CODE</b> | <b>FUNCTION</b>  |
|--------------------------|--|
| LU0                      | Turns off the active user level calibration table.   |
| LU1                      | Activates user level calibration table #1.<br>Turns off any other active user level calibration table. |
| LU2                      | Activates user level calibration table #2.<br>Turns off any other active user level calibration table. |
| LU3                      | Activates user level calibration table #3.<br>Turns off any other active user level calibration table. |
| LU4                      | Activates user level calibration table #4.<br>Turns off any other active user level calibration table. |
| LU5                      | Activates user level calibration table #5.<br>Turns off any other active user level calibration table. |
| LUR                      | Readies the 680XXB to receive five tables of user level calibration data from the controller.          |
| LUS                      | Sends all five tables of user level calibration data to the controller.                                |

The following is an example program for saving and recalling user level calibration tables. This program uses the National Instruments NI-288.2 C language interface library (mcib.lib) and header (decl.h).

```
#include <stdio.h>
#include "decl.h"

void gpiberr(char *);

#define BOARD_ID      0
#define USER_LVL_SAVE    1
#define USER_LVL_RECALL  2
#define USER_LVL_NUM_BYTES 8232

void main()
{
    Addr4882_t    source_addr = 5
                 device_addr[2] = {5, NOADDR};
    unsigned char user_lvl_tables[USER_LVL_NUM_BYTES];
    init         user_lvl_received,
                 user_input;
    FILE         *fp_user_lvl_data:

    /** Clear the bus and take control.
    **/
    SendIFC(BOARD_ID);
    if(ibsta & ERR)
        gpiberr("SendIFC error");

    /** Set the remote enable line.
    **/
    EnableRemote(BOARD_ID, device_addr);
    if(ibsta & ERR)
        gpiberr("EnableRemote error");

    /** Prompt the user to save or recall the data.
    **/
    printf("1. Save the data from the source\n");
    printf("2. Recall the data to the source\n");
    printf("Option: ");

    scanf("%d",&user_input);

    if(user_input == USER_LVL_SAVE)
        {
```

NOTE: This program is continued in Figure 2-15a.

---

**Figure 2-15.** Programming Example of Saving and Recalling User Level Calibration Tables (1 of 3)

```
/** The LUS command tells the source to send the user level
** table data over the bus.
**/
Send(BOARD_ID, source_addr, "LUS\r\n", 5L, DABend);
if(ibsta & ERR)
    gpiberr("Send error");

/** Receive the user level table data.
**/
printf("Receiving data from the source\n");
Receive(BOARD_ID, source_addr, user_lvl_tables,
        (long)USER_LVL_NUM_BYTES, STOPend);
if(ibsta & ERR)
    gpiberr("Receive error");

user_lvl_received = ibcntl;
printf("Received %d bytes of user level data\n",
        user_lvl_received);

/** Open binary data file and output the data.
**/
if((fp_user_lvl_data = fopen("userlvl.dat", "w+b")) == NULL)
    {
    printf("Can't open the userlvl.dat data file\n");
    }
else
    {
    printf("Outputting to userlvl.dat in the current
           directory\n");
    fwrite(user_lvl_tables, sizeof(user_lvl_tables[0]),
           USER_LVL_NUM_BYTES, fp_user_lvl_data);
    }
}
else
{
/** Open the binary data file and read the data.
**/
if((fp_user_lvl_data = fopen("userlvl.dat", "rb")) == NULL)
    {
    printf("Can't open the userlvl.dat data file\n");
    }
else
    {
    printf("Inputting from userlvl.dat in the current
           directory\n");
    fread(user_lvl_tables, sizeof(user_lvl_tables[0]),
           USER_LVL_NUM_BYTES, fp_user_lvl_data);
    }
}
```

NOTE: This program is continued in Figure 2-15b.

---

**Figure 2-15a.** Programming Example of Saving and Recalling User Level Calibration Tables (2 of 3)

```
/** The LUR command readies the source to receive the user
** level table data. Notice that there is no carriage
** return, line feed, or EOI sent with the LUR command.
**/
Send(BOARD_ID, source_addr, "LUR", 3L, NULLend);
if(ibsta & ERR)
    gpiberr("Send error; LUR");

/** The data is sent to the source immediately following the
** LUR command.
**/
printf("Sending %d bytes of data to the source\n",
        USER_LVL_NUM_BYTES);
Send(BOARD_ID, source_addr, user_lvl_tables,
      (long)USER_LVL_NUM_BYTES, DABend);
if(ibsta & ERR)
    gpiberr("Send error; data");
}

fclose(fp_user_lvl_data);
exit(0);
}/** end of main **/

/*****
***Name: gpiberr
**Desc: Display error code and message for all GPIB operation
**Receives: errsta - the error string to display
**Returns: nothing
**/
void gpiberr(char *errstr)
{
printf("\n%s\nError code = %d\n",errstr,iberr);
}/** end of gpiberr **/
```

---

**Figure 2-15b.** Programming Example of Saving and Recalling User Level Calibration Tables (3 of 3)

***Editing the  
Table Data***

While stored in the binary data file of the controller, the data of the five user level calibration tables can be edited. An editor that can display the data file in hexadecimal will be needed to perform the edit.

***Types of Data Storage Methods***

There are three types of data storage methods used for user level calibration data. Each is described in the following paragraphs. (The data item descriptions will refer back to these data types.)

**Double:**

8 bytes. Most significant byte first.  
ANSI/IEEE-754 64-bit floating point format.

| S | ← E → | ← F → |  
where:

S (1 bit) = sign bit, 0 positive, 1 negative  
E (11 bits) = exponent, biased by 1023 base 10  
F (52 bits) = fraction,  $0 \leq F < 1$

value =  $[(-1) \text{ raised to the } S \text{ power}] \times$   
 $[2 \text{ raised to the } (E - 1023) \text{ power}] \times$   
 $[1 + F]$

***Example:***

801 is stored as 40 89 08 00 00 00 00 00, base 16  
S = 0  
E = 408 base 16 = 1032 base 10  
F = .908 base 16 = .564453125 base 10  
801 =  $1 \times 512 \times 1.564453125$

**Integer:**

4 bytes. Most significant byte first.  
Stored as a signed integer. The sign bit is the most significant bit. Negative numbers are stored in 2's complement form.

***Example:***

7025 is stored as 00 00 1B 71, base 16  
-7025 is stored as FF FF D4 8F, base 16 2's complement

**Short:**

2 bytes. Most significant byte first.  
Stored as a signed short. The sign bit is the most significant bit. Negative numbers are stored in 2's complement form.

***Example:***

350 is stored as 01 5E, base 16  
-350 is stored as FE A2, base 16



**Data Item Descriptions**

Each data item contained in the binary data file is described below with the following information:

- Data name
- Description
- Type of data storage
- Offset into the data file for each user level calibration table
- Data units

Figure 2-16 (page 2-47) shows a printout of a section of the data file that contains each of these data items for user level calibration table #2.

**Name: Start Frequency**

Description: The starting frequency for each user level calibration.

Type: Double

Offsets (base 16): Table #1 **0006**  
Table #2 **0674**  
Table #3 **0CE2**  
Table #4 **1350**  
Table #5 **19BE**

Units: mHz (millihertz)

**Name: Stop Frequency**

Description: The ending frequency for each user level calibration.

Type: Double

Offsets (base 16): Table #1 **000E**  
Table #2 **067C**  
Table #3 **0CEA**  
Table #4 **1358**  
Table #5 **19C6**

Units: mHz (millihertz)

**Name: Frequency Increment**

Description: The frequency increment for 1 point. This value = (stop frequency – start frequency) divided by the number of points.

Type: Double

Offset (base 16): Table #1 **0016**  
Table #2 **0684**  
Table #3 **0CF2**  
Table #4 **1360**  
Table #5 **19CE**

Units: mHz (millihertz)

**Name: Number of Points**

Description: The number of frequency points.

Type: Double

Offsets (base 16): Table #1 **001E**  
Table #2 **068C**  
Table #3 **0CFA**  
Table #4 **1368**  
Table #5 **19D6**

Units: a value of 1 = 1 point

**Name: Level Correction Offset**

Description: This is the power level that is added to the front panel power before the level correction point table power levels are subtracted. It represents the maximum power deviations read during the calibration.

Type: Integer

Offsets (base 16): Table #1 **0026**  
Table #2 **0694**  
Table #3 **0D02**  
Table #4 **1370**  
Table #5 **19DE**

Units: mdB (milli-dB)

**Name: Level Correction Point Table**

Description: These are the power level correction values with respect to the maximum power deviation read during the calibration.

Type: Short (Array of 801 Points)

Offsets (base 16): Table #1 **002A**  
Table #2 **0698**  
Table #3 **0D06**  
Table #4 **1374**  
Table #5 **19E2**

Units: mdB (milli-dB)

```
000640 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
000650 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
000660 00 00 00 00 00 00 00 00 00 00 00 00 00 BA BE
000670 00 00 DA BE 42 7D 1A 94 A2 00 00 00 42 A2 30 9C
000680 E5 40 00 00 42 6D 1A 94 A2 00 00 00 40 22 00 00
000690 00 00 00 00 00 00 17 83 FF 11 FF 56 FF 56 FF 74
0006A0 FF 93 FF 9C FF F6 00 00 FF C4 D1 21 E8 37 00 00
0006B0 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
0006C0 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
0006D0 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
```

**Printout Explanation**

The printout shows a section of the user level calibration data file, in hexadecimal, that contains each of the data items for user level calibration table #2. The offset into the data file is shown at the left in the printout.

Offset 0674: Start Frequency

42 7D 1A 94 A2 00 00 00 = 2 GHz

Offset 067C: Stop Frequency

42 A2 30 9C E5 40 00 00 = 10 GHz

Offset 0684: Frequency Increment

42 6D 1A 94 A2 00 00 00 = 1 GHz

Offset 068C: Number of Points

40 22 00 00 00 00 00 00 = 9 points

Offset 0694: Level Correction Offset

00 00 17 83 = 6.016 dB

Offset 0698: Level Correction Point Table (9 points)

FF 11 = -.239 dB

FF 56 = -.170 dB

FF 56 = -.170 dB

FF 74 = -.140 dB

FF 93 = -.109 dB

FF 9C = -.100 dB

FF F6 = -.010 dB

00 00 = 0 dB

FF C4 = -.060 dB

---

**Figure 2-16.** Printout of a Section of the User Level Calibration Binary Data File

**2-17 MASTER-SLAVE  
OPERATION  
COMMANDS**

Table 2-17 lists the master-slave operation command mnemonic codes. These commands provide for enabling two 68XXXBs that are connected in a master-slave configuration to produce CW and synchronized, swept output signals at a frequency offset.

In a master-slave configuration, one 68XXXB (the Master) controls the other (the Slave) via interface cables between their rear panel AUX I/O and SERIAL I/O connectors. The two units are phase-locked together by connecting them to the same 10 MHz reference time base. (Refer to the 680XXB Operation Manual, Chapter 7—Use With Other Instruments, for master-slave interconnection and operating instructions.)

The parameter entry commands, SLF0 - SLF9 and SLM0 - SLM9, are used to set the F0 - F9 and M0 - M9 frequencies for the Slave 68XXXB; the SLDF command is used to set the  $\Delta F$  parameter for the Slave instrument. The main output power level (L1) for the Slave unit is set using the SLV or SLL1 command; the alternate sweep power level (L2) for the Slave unit is set using the SLL2 command. The S1 command turns on the master-slave mode of operation; the S0 command turns off the Master-Slave mode of operation.

***Programming Example:***

Programming “**SLF1 5 GH SLF2 8 GH SLL1 3 DM S1**” sets the Slave 68XXXB F1 frequency to 5 GHz, its F2 frequency to 8 GHz, and its output power level to 3 dBm and turns on the master-slave mode of operation. Now, when the Master 68XXXB is programmed to perform a F1 to F2 sweep, the Slave unit will produce a synchronous 5 GHz to 8 GHz frequency sweep that has an output power level of 3 dBm.

***Programming Note:***

Use the SOF command only to set the frequency offset for a Slave unit that is (1) slave to a Master 68XXXB that is connected to a 360B VNA in a source or dual-source configuration or (2) slave to a Master 68XXXB that is programmed to perform non-sequential frequency step sweeps (refer to Special Step Sweep on page 2-19).

**Table 2-17.** *Master-Slave Operation Commands*

| MNEMONIC CODE | FUNCTION                                      |
|---------------|---|
| S0            | Turns off the Master-Slave mode of operation. |
| S1            | Turns on the Master-Slave mode of operation.  |

**2-18 SELF TEST COMMAND**

Table 2-18 lists the self test command mnemonic code. This command provides for executing a CW generator self test.

When a TST command is received, the CW generator performs a self test, then places a "P" (for pass) or a "F" (for fail) on the bus. It also generates six self test results bytes. Figure 2-18 (next page) shows the six self test results bytes and identifies the reporting function of each bit.

When self test is completed, bit 7 of Self Test Results Byte 6 and bit 2 of Extended Status Byte 1 are both set. If a failure(s) occurs during self test, the Self Test Results Byte bit(s) reporting the failure(s) and bit 0 of Extended Status Byte 1 are set.

The OSR command returns the six self test results bytes to the controller. Figure 2-17 provides an example of self test command programming.

**Programming Note:** The "P or "F" character placed on the bus by the CW generator self test must be cleared from the output buffer (read by the controller) before another output command, such as OSR, is sent. If it is not cleared, the first character of the next output will be missing. Line 30 (Figure 2-17) shows clearing of the "P" or "F" character.

**Table 2-19.** Self Test Command

| MNEMONIC CODE | FUNCTION  |
|---------------|---|
| TST           | Executes a CW generator self test. Extended Status Byte 1 bit 0 is set if self test fails; bit 2 is set when self test is complete. |

```

10 OUTPUT 705; "CSB"
20 OUTPUT 705; "TST"
30 ENTER 705; D$
40 DISP D$
50 OUTPUT 705; "OSR"
60 ENTER 705 USING "#,B"; A, B, C, D, E, F
70 DISP A; B; C; D; E; F
80 END

```

**Figure 2-17.** Self Test Command Programming Example

**Self Test Results Byte 1**

|                                |                                      |  |   |   |   |   |                                      |
|--------------------------------|--------------------------------------|--|---|---|---|---|--------------------------------------|
| Sweep Time<br>Circuitry Failed | A18 Power<br>Supply is Not<br>Locked | Power Supply<br>Voltage(s) are<br>Out of Reg | A12 -10 Volt<br>Reference<br>Check Failed | A12 +10 Volt<br>Reference<br>Check Failed | DVM -10 Volt<br>Reference<br>Check Failed | DVM +10 Volt<br>Reference<br>Check Failed | DVM Ground<br>Offset Check<br>Failed |
| Bit 7<br>(128)                 | Bit 6<br>(64)                        | Bit 5<br>(32)                                | Bit 4<br>(16)                             | Bit 3<br>(8)                              | Bit 2<br>(4)                              | Bit 1<br>(2)                              | Bit 0<br>(1)                         |

**Self Test Results Byte 2**

|   |                                    |  |   |   |  |                                |                         |
|---|------------------------------------|--|---|---|--|--------------------------------|-------------------------|
| Not Locked<br>Indicator<br>Check Failed | Down Converter<br>is<br>Not Locked | YIG Loop<br>Circuitry is<br>Not Locked | Coarse Loop<br>Circuitry is<br>Not Locked | Fine Loop<br>Circuitry is<br>Not Locked | High Stability<br>Crystal is<br>Not Locked | Ext 10 MHz<br>is<br>Not Locked | Oven<br>is<br>Not Ready |
| Bit 7<br>(128)                          | Bit 6<br>(64)                      | Bit 5<br>(32)                          | Bit 4<br>(16)                             | Bit 3<br>(8)                            | Bit 2<br>(4)                               | Bit 1<br>(2)                   | Bit 0<br>(1)            |

**Self Test Results Byte 3**

|   |  |   |               |   |  |                                   |                                     |
|---|--|---|---------------|---|--|-----------------------------------|-------------------------------------|
| Detector Log<br>Amp Circuitry<br>Failed | Level Reference<br>Circuitry<br>Failed | Not Leveled<br>Detector<br>Circuitry Failed | Not Used      | Center<br>Frequency<br>Circuitry Failed | Marker Switch<br>Point<br>Circuitry Failed | Linearizer<br>Circuitry<br>Failed | FM Loop<br>Gain<br>Circuitry Failed |
| Bit 7<br>(128)                          | Bit 6<br>(64)                          | Bit 5<br>(32)                               | Bit 4<br>(16) | Bit 3<br>(8)                            | Bit 2<br>(4)                               | Bit 1<br>(2)                      | Bit 0<br>(1)                        |

**Self Test Results Byte 4**

|  |  |   |                                    |   |   |  |  |
|--|--|---|------------------------------------|---|---|--|--|
| 3.3 - 5.5 GHz<br>Switch Filter<br>Section or<br>Level Detector<br>Circuitry Failed | 2-3.3 GHz<br>Switch Filter<br>Section or<br>Level Detector<br>Circuitry Failed | Switch Filter<br>or<br>Level Detector<br>Circuitry Failed | 0.01 - 2 GHz<br>Range<br>Unleveled | A10 Q5 or<br>Associated<br>Circuitry Failed | 2 - 8.4 GHz<br>Range<br>Unleveled and<br>Not Locked | 8.4 - 20 GHz<br>Range<br>Unleveled and<br>Not Locked | 2 - 20 GHz<br>Range<br>Unleveled and<br>Not Locked |
| Bit 7<br>(128)   | Bit 6<br>(64)  | Bit 5<br>(32)   | Bit 4<br>(16)                      | Bit 3<br>(8)                                | Bit 2<br>(4)  | Bit 1<br>(2)   | Bit 0<br>(1)                                       |

**Self Test Results Byte 5**

|  |  |               |               |  |   |  |  |
|--|--|---------------|---------------|--|---|--|--|
| 32 - 40 GHz<br>Section of<br>Switched<br>Doublers Module<br>Failed | Switched<br>Doublers Module<br>or Driver<br>Circuitry Failed | Not Used      | Not Used      | Modulator or<br>Driver Circuitry<br>on A9-1 Failed | 13.25 - 20 GHz<br>Switch Filter<br>Section or<br>Level Detector<br>Circuitry Failed | 8.4 - 13.25 GHz<br>Switch Filter<br>Section or<br>Level Detector<br>Circuitry Failed | 5.5 - 8.4 GHz<br>Switch Filter<br>Section or<br>Level Detector<br>Circuitry Failed |
| Bit 7<br>(128)   | Bit 6<br>(64)  | Bit 5<br>(32) | Bit 4<br>(16) | Bit 3<br>(8)                                       | Bit 2<br>(4)  | Bit 1<br>(2)   | Bit 0<br>(1)   |

**Self Test Results Byte 6**

|                             |               |               |   |  |              |  |  |
|-----------------------------|---------------|---------------|---|--|--------------|--|--|
| Self Test<br>is<br>Complete | Not Used      | Not Used      | RF Was Off<br>When Self Test<br>Started | Slope DAC or<br>Associated<br>Circuitry Failed | Not Used     | 20 - 25 GHz<br>Section of<br>Switched<br>Doublers Module<br>Failed | 25 - 32 GHz<br>Section of<br>Switched<br>Doublers Module<br>Failed |
| Bit 7<br>(128)              | Bit 6<br>(64) | Bit 5<br>(32) | Bit 4<br>(16)                           | Bit 3<br>(8)                                   | Bit 2<br>(4) | Bit 1<br>(2)   | Bit 0<br>(1)   |

**Figure 2-18.** Self Test Results Bytes

**2-19 MISCELLANEOUS  
COMMANDS**

Table 2-19 is a list of miscellaneous command mnemonic codes that do not fit into any of the other classifications. These commands provide the following operations:

- ❑ GPIB Address Change
- ❑ CW Ramp
- ❑ Secure Mode
- ❑ Returning the 680XXB to local control
- ❑ Instrument Reset
- ❑ Serial Number Entry

**Table 2-19.** *Miscellaneous Commands*

| MNEMONIC<br>CODE   | FUNCTION  |
|--|---|
| ADD  | Permits changing of the instrument GPIB address. The address must be between 1 and 30 and must be terminated with ADR.<br><b>Programming Example:</b><br>Programming " <b>ADD 13 ADR</b> " changes the instrument GPIB address to 13. |
| CS0  | Turns off the CW ramp.  |
| CS1  | Turns on the CW ramp. This produces a repetitive 0V to 10V ramp output to the rear panel HORIZ OUT connector and pin 1 of the AUX I/O connector.  |
| DS0  | Turns on the secure mode. This blanks the front panel display of all frequency, power level, and modulation parameters.   |
| DS1  | Turns off the secure mode and restores the front panel display of all frequency, power level, and modulation parameters.  |
| RL   | Returns the 680XXB to local (front panel) control.  |
| RST  | Resets the 680XXB to its default settings.  |
| <b>NOTE</b>  |   |
| Sending this command clears the current instrument setup. If this setup is needed for future testing, save it as a stored setup (para. 2-10) before sending RST. |   |
| SNR  | Permits entry of the instrument serial number (SNRnnnnnnX). The serial number, represented by nnnnnn, must be six characters in length.   |

**2-20 PROGRAM ERRORS**

Two types of errors can occur in bus programming—invalid-parameter and syntax. These two error types are described in the following paragraphs.

***Invalid-  
Parameter***

Invalid-parameter errors are those that cause the CW generator to beep. These errors include:

- ❑ Attempting to enter a frequency, time, or power level parameter that exceeds the limits of the CW generator.
- ❑ Failing to properly end a parameter entry with a suitable terminator such as MH, DB, MS, etc.

***Syntax***

Syntax errors are those that occur in the formulation of a program statement, such as writing "EXTTFS" instead of "EXTTRS".

To prevent misinterpretation of command statements, the CW generator ignores all portions of the command statement following the syntax error.

All commands are ignored until the CW generator receives the Unlisten command (ASCII 63; "?" character) over the bus or until the CW generator is addressed to talk.



**2-21** **RESET PROGRAMMING AND DEFAULT CONDITIONS**

Table 2-20 describes the five methods that can be used to reset the CW generator. They provide a means for quickly returning the 680XXB to its default (preprogrammed) operational state.

The default settings for the numeric frequency, sweep time, and power level parameters are the same as those listed in Table 3-1 on page 3-14 of the Series 680XXB Synthesized CW Generator Operation Manual (P/N 10370-10264).

Figure 2-19 (page 2-54) provides an example of a recommended sequence for programming a reset command. Using this command sequence ensures that all parameters and commands assume their pre-programmed state each time reset is desired.

**Table 2-20.** *Resetting the 680XXB GPIB Interface Circuits*

| <b>Methods of Resetting GPIB Interface Circuits</b>        | <b>Functions Affected</b> | <b>Default Conditions</b>  |
|--|---------------------------|--|
| 1. Pressing the front panel menu RETURN TO LOCAL soft-key. | Bus Messages              | Local  |
| 2. Pressing the front panel System menu RESET soft-key.    | Service Request Modes     | ES0, FB0, PE0, SB0, SE0, SQ0, UL0, SB0<br>GTS<br>Local and Local Lockout   |
| 3. Sending the RST command over the bus.                   | Same as 2 above           | Same as 2 above except that the local bus message is not reset.            |
| 4. Executing the interface message Device Clear.           | Same as 2 above.          | Same as 2 above except that the local bus message is not reset.            |
| 5. Turning power on and off.                               | Same as 2 above.          | Places the GPIB into the power-on state. Instrument state does not change. |

---

*Sample Coding In Basic*

```
10 CLEAR 705  
20 OUTPUT 705; "FUL IL1 L1 10DM"
```

*Explanation of Code*

Line 10 sends the Device Clear bus message. This message clears the CW generator GPIB interface.

Line 20 sends new front panel settings: Full Sweep, Internal Leveling, and Output Power Level of 10 dBm.

---

**Figure 2-19.** *Reset Programming Example*

## **2-22** PROGRAMMING EXAMPLES

Figures 2-20 thru 2-22, on the following pages, provide three examples of GPIB programming using 680XXB command codes.

The following subroutine uses the output identify (OI) command to identify the CW generator's model number, serial number, minimum and maximum frequencies, minimum and maximum power level, and software revision level. This subroutine is used in the example programs in Figures 2-21 and 2-22 to read the limits of the CW generator.

```
10 ! "GET OI"  
20 ! Gets the output id string  
30 ! from a 68XXX Synthesizer  
100 OUTPUT 705; "OI"  
110 DIM A$(36)  
120 ENTER 705; A$  
130 M$=A$(1,2) ! Model  
140 M1$=A$(3,4) ! Model Number  
150 F1$=A$(5,9) ! Freq Low  
160 F2$=A$(10,14) ! Freq High  
170 L2$=A$(15,20) ! Min Power  
180 L1$=A$(21,24) ! Max Power  
190 S$=A$(25,28) ! Software Ver  
200 S1$=A$(29,34) ! Serial Number  
210 P$=A$(35,35) ! Model Prefix  
220 S2$=A$(36) ! Series  
230 PRINT "Model Number :";M$;S2$;M1$;P$  
240 PRINT "Serial Number :";S1$  
250 PRINT "Low Freq :";F1$  
260 PRINT "High Freq :";F2$  
270 PRINT "Max Power :";L1$  
280 PRINT "Min Power :";L2$  
290 PRINT "Software Ver :";S$  
300 END
```

#### **Program Explanation**

*Line 100:* Sends the "OI" command.

*Line 110:* Dimensions the variable.

*Line 120:* Gets the "OI" string.

*Line 130:* Sets M\$ to the model (68).

*Line 140:* Sets M1\$ to the model number.

*Line 150:* Sets F1\$ to the CW generator low-end frequency.

*Line 160:* Sets F2\$ to the CW generator high-end frequency.

*Line 170:* Sets L2\$ to the minimum power point.

*Line 180:* Sets L1\$ to the maximum power point.

*Line 190:* Sets S\$ to the software version number.

*Line 200:* Sets S1\$ to the serial number.

*Line 210:* Sets P\$ to the model prefix number (0,1, or 2).

*Line 220:* Sets S2\$ to the model series (A or B).

*Lines 230-290:* Prints the data obtained.

---

**Figure 2-20.** Using the Output Identify (OI) Command

The following program (1) receives entries from the keyboard to set initial frequency and step-size parameters, and (2) activates the soft keys on the controller so that they can step the frequency up or down.

**Program Explanation**

*Line 30:* Sets the address of the CW generator.  
*Line 40:* Calls the device identification subroutine described in Line 1010.  
*Line 50:* Turns off the key definitions.  
*Lines 60-110:* Accept the starting frequency entry and checks its validity.  
*Lines 120-170:* Accept the step size entry and checks its validity.  
*Line 180:* Sets the CW generator to the starting frequency and step size.  
*Lines 190-240:* Set up keys and key labels.  
*Line 250:* Waits for a key to be pressed.  
*Line 300:* Reports that the STEP UP key was pressed; sends the UP command.  
*Line 310:* Waits for the next key.  
*Line 320:* Reports that the STEP DOWN key was pressed; send the DN command.  
*Line 330:* Waits for the next key.  
*Line 340:* Ends the main program.  
*Lines 1010-1120:* Identify the CW generator address, model, frequency range, and power range.

```

20 ! PARAMETER ENTRY, SYZ, UP, AND DN COMMANDS
30 Address=705
40 CALL Iddev(Address,Model,Fmin,Fmax,Pmin,Pmax)
50 OFF KEY
60 DISP "ENTER FREQUENCY IN GHz";
70 INPUT Freq
80 IF Freq>Fmax OR Freq<Fmin THEN
90   DISP "FREQUENCY OUT OF RANGE - ";
100  GOTO 60
110 END IF
120 DISP "ENTER STEP SIZE IN GHz";
130 INPUT Stepsize
140 IF Stepsize>Fmax-Fmin OR Stepsize<.000001 THEN
150   DISP "ILLEGAL STEP SIZE - ";
160   GOTO 120
170 END IF
180 OUTPUT Address;"CF1";Freq;"GH SYZ";Stepsize;"GH"
190 ON KEY 0 LABEL "STEP" GOTO 300
200 ON KEY 5 LABEL " UP " GOTO 300
210 ON KEY 1 LABEL "STEP" GOTO 320
220 ON KEY 6 LABEL "DOWN" GOTO 320
230 ON KEY 2 LABEL "NEW " GOTO 50
240 ON KEY 7 LABEL "FREQ" GOTO 50
250 GOTO 250
300 OUTPUT Address;"UP"
310 GOTO 250
320 OUTPUT Address;"DN"
330 GOTO 250
340 END
1010 SUB Iddev(Address,Model,Fmin,Fmax,Pmin,Pmax)
1020 DIM Ident$(36)
1030 OUTPUT Address;"OI"
1040 ENTER Address;Ident$
1050 Model=VAL(Ident$(1,2))
1060 Model Number=VAL(Ident$(3,4))
1070 Fmin=VAL(Ident$(5,9))
1080 Fmax=VAL(Ident$(10,14))
1090 Pmin=VAL(Ident$(15,20))
1100 Pmax=VAL(Ident$(21,24))
1110 Model Prefix=Ident$(35,35)
1120 Series=VAL(Ident$(36))
1130 SUBEND

```

**Figure 2-21.** Controlling CW Frequency/Parameter Entries

The following program accepts user inputs for (1) power sweep starting and ending levels, (2) number of steps in the sweep, and (3) sweep dwell times. After accepting such inputs, the program then commands the CW generator to obtain a display of the power sweep.

NOTE: The CW generator should be connected to a scalar network analyzer.

#### Program Explanation

*Line 30:* Set the address of the CW generator.

*Line 40:* Call the device identification subroutine described in line 1010.

*Lines 60-110:* Accept the starting power level entry and checks its validity.

*Lines 120-170:* Accept the ending power level entry and checks its validity.

*Lines 180-230:* Accept the power sweep number-of-steps entry and checks its validity.

*Lines 240-290:* Accept the power sweep dwell time entry and checks its validity.

*Lines 300-310:* Sets the CW generator to perform the above defined power sweep.

*Line 340:* Ends the main program.

*Lines 1010-1120:* Identify the CW generator address, model, frequency range, and power range.

```

30 Address=705
40 CALL Iddev(Address,Model,Fmin,Fmax,Pmin,Pmax)
60 DISP "ENTER POWER SWEEP STARTING LEVEL (dBm)";
70 INPUT Powerstart
80 IF Powerstart>Pmax OR Powerstart<Pmin THEN
90   DISP "POWER OUT OF RANGE - ";
100  GOTO 60
110 ENDIF
120 DISP "ENTER POWER SWEEP ENDING LEVEL (dBm)";
130 INPUT Powerstop
140 IF Powerstop>Pmax OR Powerstop<Pmin THEN
150   DISP "POWER OUT OF RANGE - ";
160   GOTO 120
170 END IF
180 DISP "ENTER NUMBER OF STEPS";
190 INPUT Noofsteps
200 IF Noofsteps<1 OR Noofsteps>10000 THEN
210   DISP "NUMBER OF STEPS OUT OF RANGE - ";
220   GOTO 180
230 END IF
240 DISP "ENTER DWELL TIME AT EACH STEP (mS)";
250 INPUT Dwell
260 IF Dwell<1 OR Dwell>99000 THEN
270   DISP "DWELL TIME OUT OF RANGE - ";
280   GOTO 240
290 END IF
300 OUTPUT Address;"L1";Powerstart:"DM L2";Powerstop;
    "DM PNS";Noofsteps;"SPS"
310 OUTPUT Address;"PDT";Dwell;"MS LSP"
340 END
1010 SUB Iddev(Address,Model,Fmin,Fmax,Pmin,Pmax)
1020 DIM Ident${36}
1030 OUTPUT Address;"OI"
1040 ENTER Address;Ident$
1050 Model=VAL(Ident${1,2})
1060 Model Number=VAL(Ident${3,4})
1070 Fmin=VAL(Ident${5,9})
1080 Fmax=VAL(Ident${10,14})
1090 Pmin=VAL(Ident${15,20})
1100 Pmax=VAL(Ident${21,24})
1110 Model Prefix=Ident${35,35}
1120 Series=VAL(Ident${36})
1130 SUBEND

```

**Figure 2-22.** Controlling Power Level and Power Sweep

# Appendix A

## Index of GPIB Commands

### A-1 INTRODUCTION

This appendix provides an alphabetical index of the GPIB Product Specific Commands for the 680XXB. The index lists the command mnemonic code, a brief description of the command function, and the page number in Chapter 2 where a complete description of the command can be found.

GPIB Commands (1 of 10)

| Command Code | Function  | Page Number |
|--------------|---|-------------|
| ACW          | Activates currently scanned frequency as CW   | 2-13        |
| AD1          | Selects F1- $\Delta$ F alternate step sweep   | 2-15        |
| AD5          | Selects F5- $\Delta$ F alternate step sweep   | 2-15        |
| AD6          | Selects F6- $\Delta$ F alternate step sweep   | 2-15        |
| ADD          | Opens the GPIB address parameter  | 2-52        |
| ADR          | GPIB address terminator   | 2-11        |
| AF1          | Selects F1-F2 alternate step sweep  | 2-15        |
| AF3          | Selects F3-F4 alternate step sweep  | 2-15        |
| AFU          | Selects Full Range alternate step sweep   | 2-15        |
| AL0          | Set alternate sweep RF output level to L0   | 2-21        |
| AL1          | Set alternate sweep RF output level to L1   | 2-21        |
| AL2          | Set alternate sweep RF output level to L2   | 2-21        |
| AL3          | Set alternate sweep RF output level to L3   | 2-21        |
| AL4          | Set alternate sweep RF output level to L4   | 2-21        |
| AL5          | Set alternate sweep RF output level to L5   | 2-21        |
| AL6          | Set alternate sweep RF output level to L6   | 2-21        |
| AL7          | Set alternate sweep RF output level to L7   | 2-21        |
| AL8          | Set alternate sweep RF output level to L8   | 2-21        |
| AL9          | Set alternate sweep RF output level to L9   | 2-21        |
| AT0          | Deselects step attenuator decouple mode   | 2-24        |
| AT1          | Selects step attenuator decouple mode on  | 2-24        |
| ATT(xx)      | Sets step attenuator value to xx ( $\times 10$ dB) in ALC step attenuator decouple mode. xx is an unsigned integer between 00 and 11. | 2-24        |
| AUT          | Selects Auto sweep trigger  | 2-15        |
| BPN          | Selects $-5V$ for retrace and bandswitch blanking outputs   | 2-34        |
| BPP          | Selects $+5V$ for retrace and bandswitch blanking outputs   | 2-34        |

---

# INDEX OF GPIB COMMANDS

---

## GPIB Commands (2 of 10)

| Command Code | Function   | Page Number |
|--------------|--|-------------|
| CF0          | Set CW mode at F0, Opens F0 parameter                  | 2-13        |
| CF1          | Set CW mode at F1, Opens F1 parameter                  | 2-13        |
| CF2          | Set CW mode at F2, Opens F2 parameter                  | 2-13        |
| CF3          | Set CW mode at F3, Opens F3 parameter                  | 2-13        |
| CF4          | Set CW mode at F4, Opens F4 parameter                  | 2-13        |
| CF5          | Set CW mode at F5, Opens F5 parameter                  | 2-13        |
| CF6          | Set CW mode at F6, Opens F6 parameter                  | 2-13        |
| CF7          | Set CW mode at F7, Opens F7 parameter                  | 2-13        |
| CF8          | Set CW mode at F8, Opens F8 parameter                  | 2-13        |
| CF9          | Set CW mode at F9, Opens F9 parameter                  | 2-13        |
| CLO          | Closes the open parameter                              | 2-10        |
| CLR          | Clears data entry                                      | 2-11        |
| CM0          | Set CW mode at M0, Opens M0 parameter                  | 2-13        |
| CM1          | Set CW mode at M1, Opens M1 parameter                  | 2-13        |
| CM2          | Set CW mode at M2, Opens M2 parameter                  | 2-13        |
| CM3          | Set CW mode at M3, Opens M3 parameter                  | 2-13        |
| CM4          | Set CW mode at M4, Opens M4 parameter                  | 2-13        |
| CM5          | Set CW mode at M5, Opens M5 parameter                  | 2-13        |
| CM6          | Set CW mode at M6, Opens M6 parameter                  | 2-13        |
| CM7          | Set CW mode at M7, Opens M7 parameter                  | 2-13        |
| CM8          | Set CW mode at M8, Opens M8 parameter                  | 2-13        |
| CM9          | Set CW mode at M9, Opens M9 parameter                  | 2-13        |
| CSO          | Turns off the CW ramp                                  | 2-52        |
| CS1          | Turns on the CW ramp                                   | 2-52        |
| CSB          | Clears all GPIB status bytes                           | 2-32        |
| DB           | dB data terminator                                     | 2-11        |
| DF0          | Selects the F0- $\Delta$ F step sweep mode             | 2-14        |
| DF1          | Selects the F1- $\Delta$ F step sweep mode             | 2-14        |
| DF5          | Selects the F5- $\Delta$ F step sweep mode             | 2-14        |
| DF6          | Selects the F6- $\Delta$ F step sweep mode             | 2-14        |
| DFF          | Opens the $\Delta$ F parameter (Same as DLF)           | 2-8         |
| DFM          | Opens the $\Delta$ F parameter (Same as DLF)           | 2-8         |
| DL1          | Selects external detector leveling of the output power | 2-21        |
| DLF          | Opens the $\Delta$ F parameter                         | 2-8         |
| DM           | dBm data terminator                                    | 2-11        |
| DN           | Decrements the open parameter by the step size         | 2-10        |

# INDEX OF GPIB COMMANDS

## GPIB Commands (3 of 10)

| Command Code | Function  | Page Number |
|--------------|---|-------------|
| DS0          | Turns on the secure mode (Blanks the front panel display of Frequency and Power Level parameters) | 2-52        |
| DS1          | Turns off the secure mode and restores front panel display of all parameters                      | 2-52        |
| DU0          | Deselects Dual Step sweep mode  | 2-16        |
| DU1          | Selects Dual Step sweep mode on   | 2-16        |
| DV           | Decibel/Volt (dB/V) data terminator   | 2-11        |
| EGI          | Opens the Reference Level DAC setting parameter (in external power leveling mode)                 | 2-21        |
| EGO          | Output value of the Reference Level DAC setting in external power leveling mode                   | 2-23        |
| ELF          | Selects front panel external leveling input   | 2-23        |
| ELR          | Selects rear panel external leveling input  | 2-23        |
| EL0          | Inhibits updating of the ESB2 bit 4 (RF Unlocked)   | 2-32        |
| EL1          | Enables updating of the ESB2 bit 4 (RF Unlocked)  | 2-32        |
| ES0          | Inhibits End-of-Sweep SRQ generation  | 2-31        |
| ES1          | Enables End-of-Sweep SRQ generation   | 2-31        |
| EXT          | Selects single sweep trigger  | 2-15        |
| F0           | Opens the F0 parameter  | 2-8         |
| F1           | Opens the F1 parameter  | 2-8         |
| F2           | Opens the F2 parameter  | 2-8         |
| F3           | Opens the F3 parameter  | 2-8         |
| F4           | Opens the F4 parameter  | 2-8         |
| F5           | Opens the F5 parameter  | 2-8         |
| F6           | Opens the F6 parameter  | 2-8         |
| F7           | Opens the F7 parameter  | 2-8         |
| F8           | Opens the F8 parameter  | 2-8         |
| F9           | Opens the F9 parameter  | 2-8         |
| FB0          | Inhibits Extended Status Byte 1 SRQ generation  | 2-31        |
| FB1          | Enables Extended Status Byte 1 SRQ generation   | 2-31        |
| FRS          | Opens the frequency scaling reference multiplier parameter  | 2-34        |
| FUL          | Selects the Full Range step sweep mode  | 2-14        |
| GH           | GHz data terminator   | 2-11        |
| GTC          | Scans to the next higher preset CW frequency on a GET (Executes a "SQF" command)                  | 2-36        |
| GTD          | Steps the open parameter down by the step size on a GET (Executes a "DN" command)                 | 2-36        |
| GTF          | Executes a Fast-frequency-switching step on a GET (See "ZL, ZEL" commands)                        | 2-36        |



# INDEX OF GPIB COMMANDS

## GPIB Commands (4 of 10)

| Command Code | Function  | Page Number |
|--------------|---|-------------|
| GTL          | Steps to the next point in a dual step sweep mode on a GET (Executes a "TSS" command)         | 2-36        |
| GTO          | Disables the GET functions  | 2-36        |
| GTS          | Triggers a single sweep on a GET (Executes a "TRS" command)                                   | 2-36        |
| GTT          | Executes a complete CW generator self test on a GET (Executes a "TST" command)                | 2-36        |
| GTU          | Steps the open parameter up by the setp size on a GET (Executes an "UP" command)              | 2-36        |
| GV           | GHz per volt (GHz/V) data terminator  | 2-11        |
| HZ           | Hz data terminator  | 2-11        |
| *IDN?        | Outputs the instrument identification string  | 2-25        |
| II0          | Enables updating of the ESB2 bit 7 (Parameter Changed)  | 2-32        |
| II1          | Inhibits updating of the ESB2 bit 7 (Parameter Changed)                                       | 2-32        |
| IL1          | Selects internal leveling of the output power   | 2-21        |
| KH           | kHz data terminator   | 2-11        |
| KV           | kHz per volt (kHz/V) data terminator  | 2-11        |
| L0           | Sets RF output power level to L0  | 2-21        |
| L1           | Sets RF output power level to L1  | 2-21        |
| L2           | Sets RF output power level to L2  | 2-21        |
| L3           | Sets RF output power level to L3  | 2-21        |
| L4           | Sets RF output power level to L4  | 2-21        |
| L5           | Sets RF output power level to L5  | 2-21        |
| L6           | Sets RF output power level to L6  | 2-21        |
| L7           | Sets RF output power level to L7  | 2-21        |
| L8           | Sets RF output power level to L8  | 2-21        |
| L9           | Sets RF output power level to L9  | 2-21        |
| LE0          | Inhibits Lock Error SRQ generation  | 2-31        |
| LE1          | Enables Lock Error SRQ generation   | 2-31        |
| LOS          | Opens the level offset parameter  | 2-9         |
| LO0          | Turns off the Level Offset function   | 2-22        |
| LO1          | Turns on the Level Offset function  | 2-22        |
| LS0          | Inhibits updating of the ESB1 bit 3 (RF Locked)   | 2-32        |
| LS1          | Enables updating of the ESB1 bit 3 (RF Locked)  | 2-32        |
| LSP          | Selects the Power Sweep mode  | 2-23        |
| LUR          | Readies the 680XXB to receive five tables of user level calibration data from the controller. | 2-41        |
| LUS          | Sends all five tables of user level calibration data to the controller.                       | 2-41        |
| LU0          | Turns off the active user level calibration table   | 2-41        |

# INDEX OF GPIB COMMANDS

## GPIB Commands (5 of 10)

| Command Code | Function  | Page Number |
|--------------|---|-------------|
| LU1          | Activates user level calibration table #1             | 2-41        |
| LU2          | Activates user level calibration table #2             | 2-41        |
| LU3          | Activates user level calibration table #3             | 2-41        |
| LU4          | Activates user level calibration table #4             | 2-41        |
| LU5          | Activates user level calibration table #5             | 2-41        |
| LV0          | Turns off leveling of the output power                | 2-23        |
| M0           | Opens the M0 parameter                                | 2-8         |
| M1           | Opens the M1 parameter                                | 2-8         |
| M2           | Opens the M2 parameter                                | 2-8         |
| M3           | Opens the M3 parameter                                | 2-8         |
| M4           | Opens the M4 parameter                                | 2-8         |
| M5           | Opens the M5 parameter                                | 2-8         |
| M6           | Opens the M6 parameter                                | 2-8         |
| M7           | Opens the M7 parameter                                | 2-8         |
| M8           | Opens the M8 parameter                                | 2-8         |
| M9           | Opens the M9 parameter                                | 2-8         |
| MAN          | Selects manual (step) sweep                           | 2-16        |
| MB0          | Sets the enable mask byte for the Primary Status Byte | 2-31        |
| MB1          | Sets the enable mask byte for Extended Status Byte 1  | 2-31        |
| MB2          | Sets the enable mask byte for Extended Status Byte 2  | 2-31        |
| ME0          | Disables the marker at the active frequency           | 2-20        |
| ME1          | Enables a marker at the active frequency              | 2-20        |
| MH           | MHz data terminator                                   | 2-11        |
| MK0          | Turns off markers                                     | 2-20        |
| MS           | Milliseconds (ms) data terminator                     | 2-11        |
| MV           | MHz per volt (MHz/V) data terminator                  | 2-11        |
| NS           | Nanoseconds (ns) data terminator                      | 2-11        |
| ODF          | Outputs the $\Delta F$ frequency value in MHz         | 2-26        |
| OEM          | Outputs the Extended SRQ Mask bytes (3 binary bytes)  | 2-27        |
| OES          | Outputs all three GPIB status bytes                   | 2-27        |
| OF0          | Outputs the F0 frequency value in MHz                 | 2-25        |
| OF1          | Outputs the F1 frequency value in MHz                 | 2-25        |
| OF2          | Outputs the F2 frequency value in MHz                 | 2-25        |
| OF3          | Outputs the F3 frequency value in MHz                 | 2-25        |
| OF4          | Outputs the F4 frequency value in MHz                 | 2-25        |
| OF5          | Outputs the F5 frequency value in MHz                 | 2-25        |
| OF6          | Outputs the F6 frequency value in MHz                 | 2-25        |

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# INDEX OF GPIB COMMANDS

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## GPIB Commands (6 of 10)

| Command Code | Function  | Page Number |
|--------------|---|-------------|
| OF7          | Outputs the F7 frequency value in MHz             | 2-25        |
| OF8          | Outputs the F8 frequency value in MHz             | 2-25        |
| OF9          | Outputs the F9 frequency value in MHz             | 2-25        |
| OFH          | Outputs the high-end frequency value in MHz       | 2-25        |
| OFL          | Outputs the low-end frequency value in MHz        | 2-25        |
| OI           | Outputs the instrument identification string      | 2-25        |
| OL0          | Outputs the L0 power level value in dBm           | 2-26        |
| OL1          | Outputs the L1 power level value in dBm           | 2-26        |
| OL2          | Outputs the L2 power level value in dBm           | 2-26        |
| OL3          | Outputs the L3 power level value in dBm           | 2-26        |
| OL4          | Outputs the L4 power level value in dBm           | 2-26        |
| OL5          | Outputs the L5 power level value in dBm           | 2-26        |
| OL6          | Outputs the L6 power level value in dBm           | 2-26        |
| OL7          | Outputs the L7 power level value in dBm           | 2-26        |
| OL8          | Outputs the L8 power level value in dBm           | 2-26        |
| OL9          | Outputs the L9 power level value in dBm           | 2-26        |
| OLO          | Outputs the Level Offset power level in dB        | 2-26        |
| OM0          | Outputs the M0 frequency value in MHz             | 2-25        |
| OM1          | Outputs the M1 frequency value in MHz             | 2-25        |
| OM2          | Outputs the M2 frequency value in MHz             | 2-25        |
| OM3          | Outputs the M3 frequency value in MHz             | 2-25        |
| OM4          | Outputs the M4 frequency value in MHz             | 2-25        |
| OM5          | Outputs the M5 frequency value in MHz             | 2-26        |
| OM6          | Outputs the M6 frequency value in MHz             | 2-26        |
| OM7          | Outputs the M7 frequency value in MHz             | 2-26        |
| OM8          | Outputs the M8 frequency value in MHz             | 2-26        |
| OM9          | Outputs the M9 frequency value in MHz             | 2-26        |
| OPD          | Outputs the power sweep dwell time in ms          | 2-26        |
| OPS          | Outputs the power sweep number of steps           | 2-26        |
| OSB          | Outputs the Primary Status Byte (1 binary byte)   | 2-27        |
| OSD          | Outputs the step sweep dwell time in ms           | 2-26        |
| OSE          | Outputs the last GPIB syntax error                | 2-27        |
| OSM          | Outputs the primary SRQ Mask byte (1 binary byte) | 2-27        |
| OSR          | Outputs the self-test results (6 binary bytes)    | 2-27        |
| OSS          | Outputs the step sweep number of steps            | 2-26        |
| OST          | Outputs the sweep time value in ms                | 2-26        |
| OVN          | Outputs the ROM version number string             | 2-26        |

# INDEX OF GPIB COMMANDS

## GPIB Commands (7 of 10)

| Command Code           | Function   | Page Number |
|------------------------|--|-------------|
| OWT                    | Outputs the GPIB termination status; 0 = CR, 1 = CRLF  | 2-27        |
| PCT                    | Percent (%) data terminator  | 2-11        |
| PCV                    | Percent per volt (%/V) data terminator   | 2-11        |
| PDT                    | Opens the power sweep dwell time parameter   | 2-9         |
| PE0                    | Inhibits Parameter Range Error SRQ generation  | 2-31        |
| PE1                    | Enables Parameter Range Error SRQ generation   | 2-31        |
| PL1                    | Selects external power meter leveling of the output power                                      | 2-23        |
| PNS                    | Opens the power sweep number of steps parameter  | 2-9         |
| PPO                    | Selects normally-open contacts on the pen lift relay   | 2-34        |
| PPC                    | Selects normally-closed contacts on the pen lift relay   | 2-34        |
| PT0                    | Disables the Power Offset Table  | 2-38        |
| PT1                    | Enables the Power Offset Table   | 2-38        |
| PTC                    | Changes a Power Offset Table entry   | 2-38        |
| PTL                    | Loads a Power Offset Table   | 2-38        |
| PVT                    | Opens the ALC power slope pivot point frequency parameter                                      | 2-9         |
| RO0                    | Selects RF to be on at reset   | 2-34        |
| RO1                    | Selects RF to be off at reset  | 2-34        |
| RC0                    | Selects RF off during frequency switching in CW or step sweep modes                            | 2-34        |
| RC1                    | Selects RF on during frequency switching in CW or step sweep modes                             | 2-34        |
| RCF                    | Readies the 680XXB to receive a new instrument setup from the controller                       | 2-27        |
| RCM                    | Readies the 680XXB to receive a new instrument setup and new stored setups from the controller | 2-27        |
| RF0                    | Turns off the RF output  | 2-22        |
| RF1                    | Turns on the RF output   | 2-22        |
| RL                     | Returns the instrument to local control  | 2-52        |
| RR0                    | Selects 0V for the ramp rest point   | 2-34        |
| RR1                    | Selects 10V for the ramp rest point  | 2-34        |
| RSN(M <sub>1-9</sub> ) | Recalls an instrument setup stored in internal setup memory location M, where M = 1 to 9.      | 2-27        |
| RSS                    | Reset a sweep if in progress   | 2-16        |
| RST                    | Resets the instrument to its default settings  | 2-52        |
| RT0                    | Selects RF to be off during retrace  | 2-34        |
| RT1                    | Selects RF to be on during retrace   | 2-34        |
| S0                     | Turns off the Master-Slave mode of operation   | 2-49        |
| S1                     | Turns on the Master-Slave mode of operation  | 2-49        |
| SAF                    | Outputs the current instrument setup to the controller   | 2-27        |

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# INDEX OF GPIB COMMANDS

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## GPIB Commands (8 of 10)

| Command Code | Function   | Page Number |
|--------------|--|-------------|
| SAM          | Outputs the current instrument setup and all stored setups to the controller | 2-27        |
| SB0          | Inhibits Extended Status Byte 2 SRQ generation                               | 2-31        |
| SB1          | Enables Extended Status Byte 2 SRQ generation                                | 2-31        |
| SDT          | Opens the step sweep dwell time parameter                                    | 2-9         |
| SE0          | Inhibits Syntax Error SRQ generation   | 2-32        |
| SE1          | Enables Syntax Error SRQ generation  | 2-32        |
| SEC          | Seconds data terminator  | 2-11        |
| SF1          | Selects the F1-F2 step sweep mode  | 2-14        |
| SF3          | Selects the F3-F4 step sweep mode  | 2-14        |
| SLDF         | Opens the $\Delta F$ parameter for the Slave unit                            | 2-9         |
| SLF0         | Opens the F0 parameter for the Slave unit                                    | 2-8         |
| SLF1         | Opens the F1 parameter for the Slave unit                                    | 2-8         |
| SLF2         | Opens the F2 parameter for the Slave unit                                    | 2-8         |
| SLF3         | Opens the F3 parameter for the Slave unit                                    | 2-8         |
| SLF4         | Opens the F4 parameter for the Slave unit                                    | 2-8         |
| SLF5         | Opens the F5 parameter for the Slave unit                                    | 2-8         |
| SLF6         | Opens the F6 parameter for the Slave unit                                    | 2-8         |
| SLF7         | Opens the F7 parameter for the Slave unit                                    | 2-8         |
| SLF8         | Opens the F8 parameter for the Slave unit                                    | 2-8         |
| SLF9         | Opens the F9 parameter for the Slave unit                                    | 2-8         |
| SLL1         | Opens the main power level parameter (L1) for the Slave unit                 | 2-10        |
| SLL2         | Opens the alternate sweep power level parameter (L2) for the Slave unit      | 2-10        |
| SLM0         | Opens the M0 parameter for the Slave unit                                    | 2-9         |
| SLM1         | Opens the M1 parameter for the Slave unit                                    | 2-9         |
| SLM2         | Opens the M2 parameter for the Slave unit                                    | 2-9         |
| SLM3         | Opens the M3 parameter for the Slave unit                                    | 2-9         |
| SLM4         | Opens the M4 parameter for the Slave unit                                    | 2-9         |
| SLM5         | Opens the M5 parameter for the Slave unit                                    | 2-9         |
| SLM6         | Opens the M6 parameter for the Slave unit                                    | 2-9         |
| SLM7         | Opens the M7 parameter for the Slave unit                                    | 2-9         |
| SLM8         | Opens the M8 parameter for the Slave unit                                    | 2-9         |
| SLM9         | Opens the M9 parameter for the Slave unit                                    | 2-9         |
| SL0          | Turns off the ALC power slope function                                       | 2-24        |
| SL1          | Turns on the ALC power slope function  | 2-24        |
| SLP          | Opens the ALC power slope value parameter                                    | 2-9         |

# INDEX OF GPIB COMMANDS

## GPIB Commands (9 of 10)

| Command Code           | Function  | Page Number |
|------------------------|---|-------------|
| SLV                    | Opens the main power level parameter (L1) for the Slave unit (Same as SLL1)                                       | 2-10        |
| SM                     | Recalls the next stored instrument setup in sequence  | 2-28        |
| SNR                    | Enter the instrument serial number (SNRnnnnnnX)   | 2-52        |
| SNS                    | Opens the step sweep number of steps parameter  | 2-9         |
| SOF                    | Opens the frequency offset parameter for the Slave unit   | 2-10        |
| SPS                    | Steps data terminator   | 2-11        |
| SP0                    | Deselects non-equally spaced step sweep   | 2-19        |
| SP1                    | Selects non-equally spaced step sweep   | 2-19        |
| SQ0                    | Disables the SRQ generation function  | 2-32        |
| SQ1                    | Enables the SRQ generation function   | 2-32        |
| SQD                    | Scan down to next lower preset CW frequency   | 2-13        |
| SQF                    | Scan to next higher preset CW frequency   | 2-13        |
| SQU                    | Scan up to next higher preset CW frequency  | 2-13        |
| SSN(M <sub>1-9</sub> ) | Saves the current instrument setup in internal setup memory location M, where M = 1 to 9                          | 2-27        |
| SSP                    | Selects step sweep  | 2-17        |
| SWT                    | Opens the analog sweep and CW ramp time parameter   | 2-9         |
| SYZ                    | Opens the increment/decrement step size parameter   | 2-12        |
| TMS                    | Times terminator  | 2-11        |
| TR0                    | Sets 0 dB of attenuation when RF is switched off in units with a step attenuator (Option 2) installed.            | 2-35        |
| TR1                    | Sets 40 dB (minimum) of attenuation when RF is switched off in units with a step attenuator (Option 2) installed. | 2-35        |
| TRG                    | Triggers a single sweep   | 2-16        |
| TRS                    | Triggers a single sweep   | 2-16        |
| TSS                    | Advances sweep to next step in dual step sweep mode   | 2-16        |
| TST                    | Starts an instrument self-test  | 2-50        |
| UL0                    | Inhibits RF Unleveled SRQ generation  | 2-32        |
| UL1                    | Enables RF Unleveled SRQ generation   | 2-32        |
| UP                     | Increment the open parameter by step size   | 2-10        |
| US                     | Microseconds (μs) data terminator   | 2-11        |
| VM1                    | Turns on the Video marker mode  | 2-20        |
| XL0                    | Opens the L0 parameter  | 2-8         |
| XL1                    | Opens the L1 parameter  | 2-8         |
| XL2                    | Opens the L2 parameter  | 2-8         |
| XL3                    | Opens the L3 parameter  | 2-8         |
| XL4                    | Opens the L4 parameter  | 2-8         |
| XL5                    | Opens the L5 parameter  | 2-8         |

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# **INDEX OF GPIB COMMANDS**

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## GPIB Commands (10 of 10)

| <b>Command Code</b>       | <b>Function</b>   | <b>Page Number</b> |
|---------------------------|---|--------------------|
| XL6                       | Opens the L6 parameter  | 2-8                |
| XL7                       | Opens the L7 parameter  | 2-8                |
| XL8                       | Opens the L8 parameter  | 2-8                |
| XL9                       | Opens the L9 parameter  | 2-8                |
| Y                         | Equivalent to a Group Excute Trigger (GET)  | 2-36               |
| ZL(X <sub>000-999</sub> ) | Loads a CW frequency into the stack at location X (fast-frequency-switching mode) | 2-37               |
| ZEL                       | Ends frequency loading (fast-frequency-switching mode)                            | 2-37               |
| ZS(X <sub>000-999</sub> ) | Sets the stack pointer to point to location X (fast-frequency-switching mode)     | 2-37               |